

Summary on Data Modeling

$$\textcircled{1} L_{\text{Rel}} = e^{-\frac{\Delta X^2}{2}} \quad \Delta X^2 \equiv \Delta^T \cdot C^{-1} \cdot \Delta - \chi_{\text{min}}^2$$

$$\Delta^T = (y_{\text{obs}} - y_{\text{theory}})_{1 \times N}$$

C = Covariance Matrix for observation

for diagonal C we have.

$$\rightarrow \Delta X^2 = \sum_{i=1}^N \frac{[y_{\text{obs}}(x_i) - y_{\text{theory}}(x_i; \theta)]^2}{\sigma_i^2} - \chi_{\text{min}}^2$$

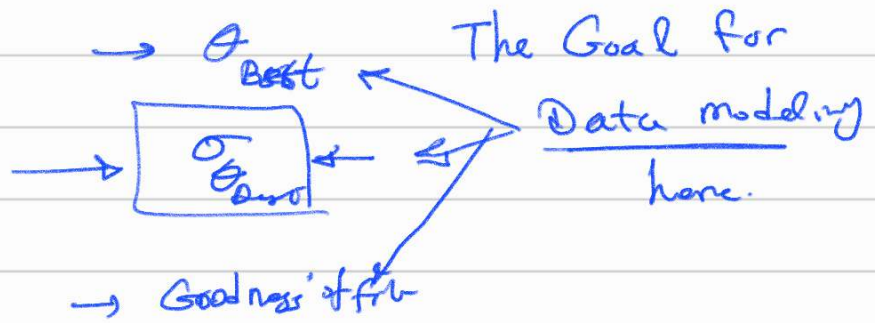
عبارت میں کوواریانس $\rightarrow \sigma_i^2$

$$\chi_{\text{min}}^2 = \chi^2(\theta_{\text{best}})$$

$$\textcircled{2} L_{\text{Rel}} = \sqrt{\frac{\text{Det}(F)}{(2\pi)^M}} e^{-\frac{\Delta\theta^T \cdot F \cdot \Delta\theta}{2}}$$

$$\Delta\theta^T = (\theta - \theta_{\text{best}})_{1 \times M}$$

$$F = \begin{bmatrix} \quad \quad \quad \end{bmatrix}_{M \times M} \rightarrow C_{\theta} = F^{-1}$$



① and ② →

$$L_{\text{Rel}} = e^{-\frac{\Delta X^2}{2}} = \sqrt{\frac{\text{Det}(F)}{(2\pi)^M}} e^{-\frac{\Delta \theta^T \cdot F \cdot \Delta \theta}{2}}$$

$$\rightarrow \ln L_{\text{Rel}} = -\frac{\Delta X^2}{2} = -\frac{\Delta \theta^T \cdot F \cdot \Delta \theta}{2} + \ln(\quad)$$

③ $F_{ij} = - \left\langle \frac{\partial^2 \ln L_{\text{Rel}}}{\partial \theta_i \partial \theta_j} \right\rangle_{\theta = \theta_{\text{Best}}}$

$$= \frac{1}{2} \left\langle \frac{\partial^2 \Delta X^2}{\partial \theta_i \partial \theta_j} \right\rangle_{\theta = \theta_{\text{Best}}}$$

④ $f \equiv \underbrace{-\ln L_{\text{rel}}}_{\Delta \chi^2} \begin{cases} \Delta \chi^2 \\ F \end{cases}$

$\rightarrow f = \frac{1}{2} \text{Tr}(\underbrace{\Delta^T \cdot C^{-1} \cdot \Delta}_{\chi^2}) + \text{cts}$

Recall
 $\text{Tr}(AB) = \text{Tr}(BA)$

⑤ $\frac{\partial f}{\partial \theta_i} = \text{Tr} \left(C^{-1} \frac{\partial}{\partial \theta_i} (\Delta^T \Delta) \right)$

Annotations:
 - C^{-1} is constant w.r.t θ_i
 - $\frac{\partial}{\partial \theta_i}$ is due to Δ
 - Δ is y_{theory}

$\left\langle \frac{\partial f}{\partial \theta_i} \right\rangle = \text{Tr} \left(C^{-1} \left\langle (\Delta^T \Delta)_{;i} \right\rangle \right)$

Since according to our condition the min value of χ^2 is associated to the best value of parameter therefore χ^2_{min} is extremum $\left\langle \frac{\partial f}{\partial \theta_i} \right\rangle = 0$

$C = \text{Diagonal: } f = \sum \frac{[y_{\text{obs}} - y_{\text{the}}(x_i, \theta)]^2}{\sigma_i^2}$

$\Rightarrow \left\langle \frac{\partial f}{\partial \theta_i} \right\rangle = \sum \frac{2}{\sigma_i^2} \frac{\partial y_{\text{the}}}{\partial \theta_i} \left[y_{\text{obs}} - y_{\text{the}} \right] \Big|_{\theta = \theta_{\text{best}}}$

$$\textcircled{6} \quad \frac{\partial^2 f}{\partial \theta_i \partial \theta_j} = \text{Tr} \left[C^{-1} (\Delta^T \Delta)_{ij} \right]$$

$$= \text{Tr} \left[\Delta_{ji}^T \cdot C^{-1} \cdot \Delta_{ij} \right]$$

$$F_{ij} = \left\langle \frac{\partial^2 f}{\partial \theta_i \partial \theta_j} \right\rangle = \text{Tr} \left[\left\langle \Delta_{ji}^T \cdot C^{-1} \cdot \Delta_{ij} \right\rangle \right]$$

\downarrow $\theta \rightarrow \theta_{best}$ $\theta \rightarrow \theta_{best}$

$$F_{ij} = \text{Tr} \left[\left\langle \frac{\partial y_{the}}{\partial \theta_i} \cdot C^{-1} \cdot \frac{\partial y_{the}}{\partial \theta_j} \right\rangle \right]$$

Diagonal C so.

$$\Delta X^2 = \sum_{i=1}^N \frac{[y_{obs} - y_{the}(\kappa_i, \theta)]^2}{\sigma_i^2}$$

$$F_{ij} = \frac{1}{2} \left\langle \frac{\partial^2 \Delta X^2}{\partial \theta_i \partial \theta_j} \right\rangle = ?$$

$$\frac{\partial \Delta X^2}{\partial \theta_i} = \sum_{i=1}^N 2 \frac{\partial y_{the}}{\partial \theta_i} \frac{[y_{obs} - y_{the}]}{\sigma_i^2}$$

$$\frac{\partial^2 \Delta X^2}{\partial \theta_i \partial \theta_j} = \sum_{i=1}^N \left\{ 2 \frac{\partial^2 y_{+n}}{\partial \theta_i \partial \theta_j} \left[\frac{1}{\sigma_i^2} \right] \right.$$

$$\left. + 2 \frac{\partial y_{+n}}{\partial \theta_i} \frac{\partial y_{+n}}{\partial \theta_j} \frac{1}{\sigma_i^2} \right\}$$

$$F_{ij} = \frac{1}{2} \left\langle \frac{\partial^2 \Delta X^2}{\partial \theta_i \partial \theta_j} \right\rangle_{\theta = \theta_{\text{best}}} = \sum_{i=1}^N \frac{1}{\sigma_i^2} \frac{\partial y_{+n}}{\partial \theta_i} \frac{\partial y_{+n}}{\partial \theta_j}$$

σ $\sigma_{\theta_1}, \sigma_{\theta_2}, \dots, \sigma_{\theta_n}$ θ_{best}

⑦ F_{ij} 's $\checkmark \longrightarrow F = \checkmark$

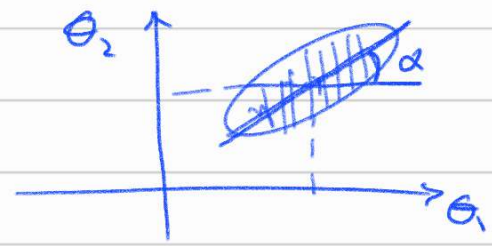
$$\sigma_{\theta_i} = (F^{-1})_{ii}$$

⑧ Determining the Contour Plot

M=2 $\delta \theta^T \cdot F \cdot \delta \theta = \Delta X^2$

$$\frac{\delta \theta_1^2}{\sigma_{11}^2 (1-\rho^2)} + \frac{\delta \theta_2^2}{\sigma_{22}^2 (1-\rho^2)} - \frac{2\rho}{(1-\rho^2)} \frac{\delta \theta_1}{\sigma_{11}} \frac{\delta \theta_2}{\sigma_{22}} = \Delta X^2$$

$$\tan 2\alpha = \frac{2\sigma_{11}\sigma_{22}}{\sigma_{22}^2 - \sigma_{11}^2}$$

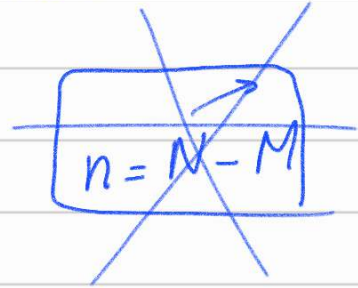


⑨ for a given Confidence interval.

$P\% = \checkmark$

$$P\% = \int_0^{\Delta\chi^2} d\Delta\chi^2 \frac{P(\Delta\chi^2)}{n}$$

$n=2$



$$P_n(\Delta\chi^2) = \frac{1}{2^{n/2} \Gamma(n/2)} (\Delta\chi^2)^{n/2} e^{-\frac{\Delta\chi^2}{2}}$$

1σ , 2σ 3σ

⑩ Goodness of fit ↔ χ^2 برائے

$$P_{<P_{obs}} = 2 P_{\chi^2 > \chi^2_{obs}} = 2 \int_{\chi^2_{obs}}^{+\infty} d\chi^2 P(\chi^2, \nu)$$

$\nu = N - M$

for $v \gg 1$ $P(x^2, v) \rightarrow$ Gaussian funct.
 $\sim e^{-\frac{(x^2 - v)^2}{2(2v)}}$

$$x^2 = v \pm \sqrt{2v}$$

$$x^2 = \frac{v}{v} \pm \frac{\sqrt{2v}}{v} = 1 \pm \sqrt{\frac{2}{v}}$$

11 How to Compute (Determine) the minimum value of χ^2 ?

(A) Fully Numerical approach \rightarrow $\begin{cases} \text{HMC} \\ \text{MCMC: } \underline{\text{Random Searching}} \\ \underline{\text{Deterministic Searching}} \end{cases}$

(B) Normal Equation \rightarrow Singular Value Decomposition

$\{\theta\}_{\text{best}}$ ✓

(C) Gradient Method $\underline{\chi^2}$ روش مبتنی بر گرادیان

$$\vec{\nabla} \chi^2 = \sum_{k=1}^M \frac{\partial \chi^2}{\partial \theta_k} \hat{\theta}_k$$

$$(\nabla \chi^2)_k = \frac{\partial \chi^2}{\partial \theta_k} = \frac{\chi^2(\theta_k + \Delta \theta_k) - \chi^2(\theta_k)}{\Delta \theta_k}$$

$$b_k \equiv \frac{\theta_k}{\Delta \theta_k}$$

$$\frac{\partial X^2}{\partial b_k} = \frac{\partial X^2}{\partial \theta_k} \Delta \theta_k$$

$$\gamma_i = \frac{\frac{\partial X^2}{\partial b_i}}{\sqrt{\sum_{k=1}^M \left(\frac{\partial X^2}{\partial b_k} \right)^2}}$$

Unit vector for Gradient

$$\theta_i(t+1) = \theta_i(t) - \gamma_i \Delta \theta_i$$

تقریباً برائے ہر کسی وقت کہیں
 نہ χ^2 کم ہو۔

according to this approach
 we essentially go to the
 value for which the $\chi^2 \rightarrow \chi^2_{min}$