

Hamiltonian Monte Carlo (HMC)

① Markov chain Monte Carlo (MCMC)

Recall that a typical classification of stochastic processes can be represented as follows:

(A) Independent Processes
Completely Random (مکمل طور پر بے ترتیب)

Dependent Parameter

$$\{x\} : \{x_1(t_1), x_2(t_2), \dots, x_N(t_N)\}$$

Independent Parameter

Time-Series

$$P(x_N, t_N; x_{N-1}, t_{N-1}; x_{N-2}, t_{N-2}; \dots; x_1, t_1)$$

$$= P(x_N, t_N) P(x_{N-1}, t_{N-1}) \dots P(x_1, t_1)$$

No-Correlation $\rightarrow \langle x(t) x(t') \rangle = \delta_D(t-t')$

(B) Dependent Stochastic Processes

Correlation time scale (دائری) فرائیڈ ہول حیثیت دائری

$$P(x_N, t_N; x_{N-1}, t_{N-1}; \dots; x_1, t_1)$$

N-Joint PDF

$$= P(x_N, t_N | x_{N-1}, t_{N-1}; x_{N-2}, t_{N-2}; \dots; x_1, t_1)$$

$P(x_N, t_N)$

$$p(x_{N-1}, t_{N-1}) \underbrace{p(x_{N-1}, t_{N-1} | x_{N-2}, t_{N-2}) \dots}_{\text{Markov property}} p(x_1, t_1)$$

$$p(x_2, t_2 | x_1, t_1) p(x_1, t_1)$$

$$p(x_2, t_2)$$

© Markov Processes فرآیندهای مارکوف

$$p(x_N, t_N | x_{N-1}, t_{N-1}, \dots, x_1, t_1) = p(x_N, t_N | x_{N-1}, t_{N-1})$$

$$\times p(x_{N-1}, t_{N-1} | x_{N-2}, t_{N-2}) \times \dots \times p(x_2, t_2 | x_1, t_1)$$

$$p(x_1, t_1)$$

$$p(x_N, t_N | x_{N-1}, t_{N-1}, x_{N-2}, t_{N-2}, \dots, x_2, t_2, x_1, t_1)$$

$$= p(x_N, t_N | x_{N-1}, t_{N-1})$$

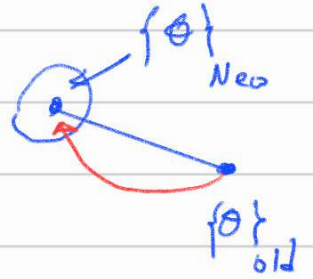
از بعد دیگری حالت فرآیندهای مارکوف

↑ New Poside
old

MCMC algorithm for optimization

Import Data. $\rightarrow \{D\} : f(x_i, y_i) \quad i=1, N$
 $f(\theta), f(\theta_j), \quad j=1, M$

Select $f(\theta)_{old}$, $L_{old} \sim \exp(-\chi_{old}^2(f(\theta)_{old}))$



loop on MCMC $\rightarrow Q(M_{MCMC})$

Select $f(\theta)_{New}$ from $f(\theta)_{old}$

Compute $\chi_{New}^2(f(\theta)_{New})$

$$\Delta \chi^2 \equiv \chi_{New}^2(f(\theta)_{New}) - \chi_{old}^2(f(\theta)_{old})$$

check acceptance Rate

$$AC \equiv \min \left\{ 1, e^{-\Delta \chi^2 / 2} \right\}$$

Metropolis algorithm

ξ = call Random number

if $\xi \leq e^{-\Delta \chi^2 / 2}$ then

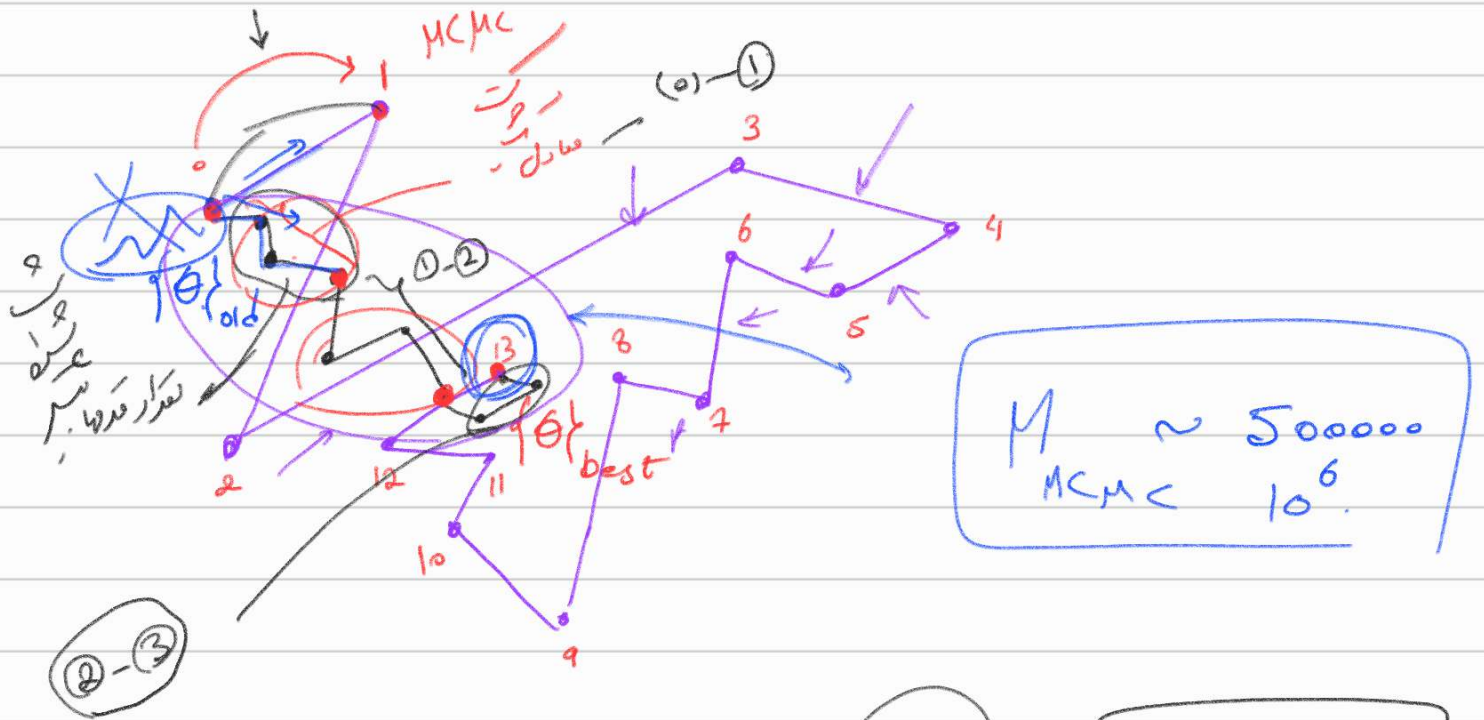
$$f(\theta)_{old} = f(\theta)_{New}$$

$$\chi_{old}^2 = \chi_{New}^2$$

End if

write $\theta_{old}^2, x_{old}^2$

End loop



0-1
انتقال

1-2
انتقال

2-3
انتقال

Best location

هدف مندر، خوشتر استراتژی است

$\theta_{old} \rightarrow \theta_{new}$

معادلات کوفه سین بر هامیله $\theta_{old} \rightarrow \theta_{new}$ \rightarrow HMC

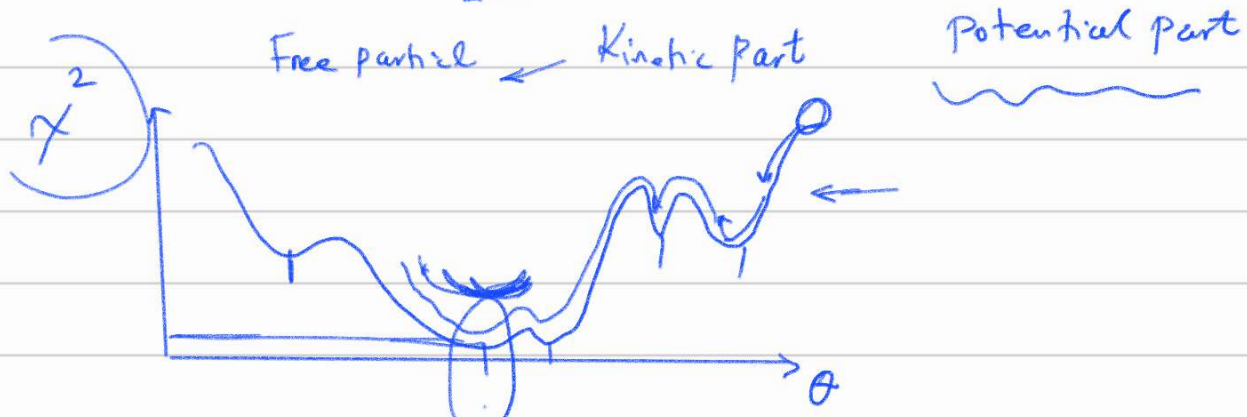
② Hamiltonian Monte Carlo (HMC)

هامیله

نویس MCMC به کمک الوریسی میسر است

more complex than MCMC

$$H(\{u\}, \{\theta\}) = \underbrace{K(\{u\})}_{\text{Kinetic part}} + \underbrace{V(\{\theta\})}_{\text{Potential part}}$$



$\frac{p^2}{2m}$

$\{\theta\}_{Best}$

$H(\{u\}, \{\theta\}) = \frac{u^T u}{2} + \frac{\chi^2(\{\theta\})}{2}$

انرژی جنبشی (Kinetic energy) انرژی پتانسیل (Potential energy)

کمینه کردن این حاصله نریخت $\{\theta\}_{Best}$

finding min of $\chi^2 \rightarrow$ finding min of $\underline{H(u, \theta)}$

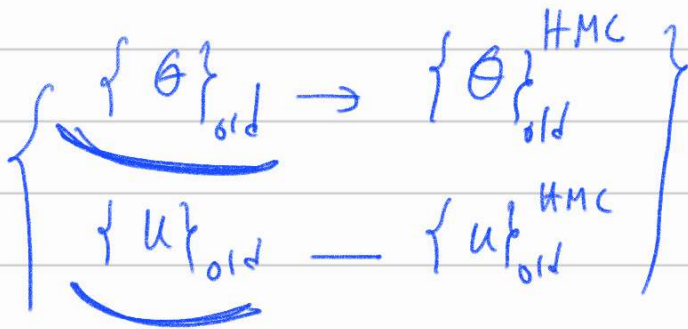
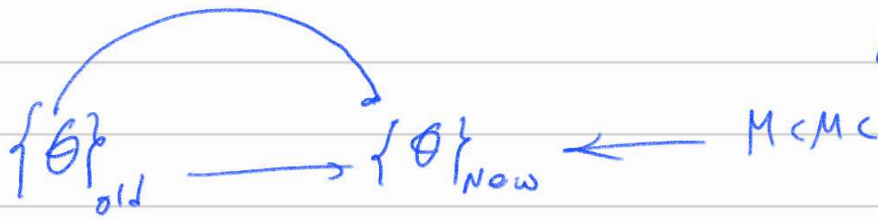
$$L = \bar{e} \frac{\chi^2}{2} \xrightarrow{HMC} L = \bar{e}^{-H}$$

$$\min \{ H(\{u\}, \{\theta\}) \} = H(\{u\}, \{\theta\}_{Best})$$

به کمینه افزایی و البته مابقی ظاهر شود

$$\mathcal{L}_{HMC} \sim e^{-\mathcal{H}} \sim \mathcal{L}(f\theta | \{\theta\}) \mathcal{N}(u, 0, 1)$$

$$e^{-\frac{u^T u}{2}}$$



Some Interesting Properties

$$\mathcal{H}(f\theta, fu) = K(fu) + V(f\theta)$$

$$\mathcal{H} = \frac{u^T u}{2} + \frac{\chi^2(f\theta)}{2}$$

$$f\theta \rightarrow \dot{\theta}$$

$$fu \rightarrow \dot{u}$$

$$\dot{p} = - \frac{\partial \mathcal{H}}{\partial q}$$

$$\dot{q} = \frac{\partial \mathcal{H}}{\partial p}$$

$$\dot{u} = - \frac{\partial \mathcal{H}}{\partial u}, \quad \dot{\theta} = \frac{\partial \mathcal{H}}{\partial \theta}$$

Recall

$$\frac{dp}{dt} = -\frac{\partial \mathcal{H}}{\partial \theta}$$

$$\frac{d\theta}{dt} = \frac{\partial \mathcal{H}}{\partial p}$$

$$\mathcal{H} = \frac{p^2}{2} + \frac{1}{2} \theta^2$$

↙ ↘
kinetic potential

$$\dot{p} = -\frac{\partial \mathcal{H}}{\partial \theta} = -\theta$$

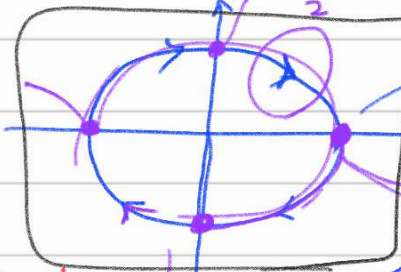
$$\dot{\theta} = p \rightarrow \ddot{\theta} = \dot{p}$$

$$\ddot{\theta} = -\theta \rightarrow \ddot{\theta} + \theta = 0$$

$$q(t) = C_1 \cos(t)$$

$$p(t) = -\sin(t)$$

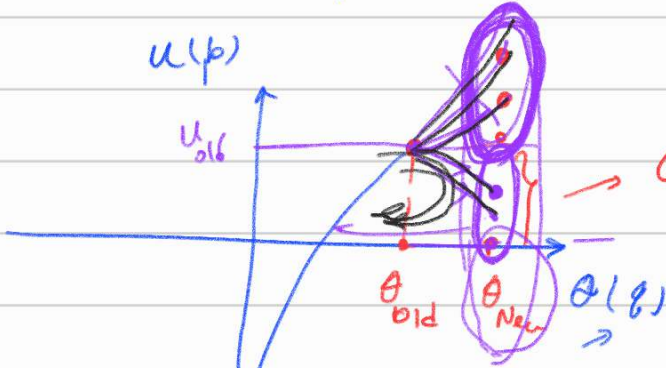
$t \leq \pi$
 $\theta = 1$
 $p = 0$



$(q, p)(t \rightarrow 0) = (1, 0)$
 $q(t \rightarrow 0) = C_1 \cos(0) = 1$
 $p(t \rightarrow 0) = -\sin(0) = 0$
 $t \rightarrow \pi/2 \rightarrow q(t \rightarrow \pi/2) = C_1 \cos(\pi/2) = 0$
 $p(t \rightarrow \pi/2) = -\sin(\pi/2) = -1$

$u(p)$

u_{old}



$$\mathcal{X}(\theta_{old}) < \mathcal{X}(\theta_{new})$$

$$\dot{p} = -\frac{\partial \mathcal{H}}{\partial \theta}$$

$$\dot{u} = -\frac{\partial \mathcal{H}}{\partial \theta} = -\frac{\partial}{\partial \theta} \left\{ \frac{u^2}{2} + \frac{\mathcal{X}^2}{2} \right\}$$

$$\dot{u} = -\frac{1}{2} \frac{\partial \mathcal{X}^2}{\partial \theta}$$

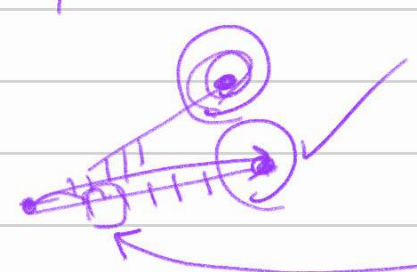
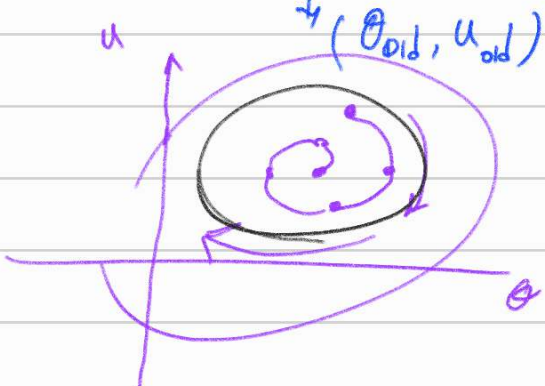
$$\mathcal{X}^2(\theta_1) < \mathcal{X}^2(\theta_2)$$

$$\frac{\partial \mathcal{X}^2}{\partial \theta} > 0$$

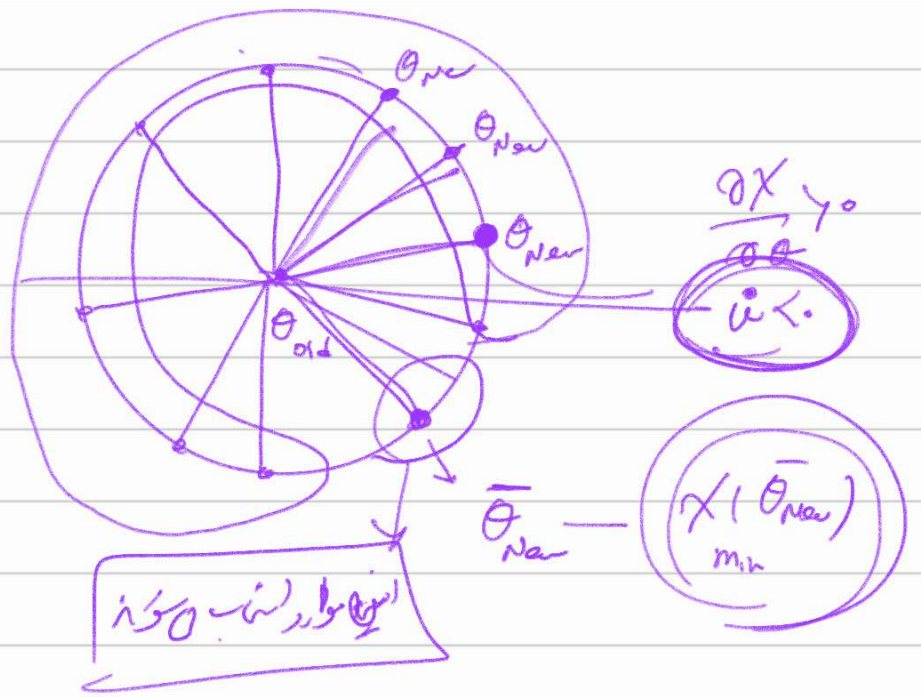
$$u < 0$$

$$u(i+1) - u(i) < 0$$

↓ ↓
 u_{new} u_{old}



θ_{old}



$$H(\theta, u) = \frac{u^2}{2} + \frac{\chi^2(\theta)}{2} \longleftrightarrow \frac{p^2}{2m} + V(\theta)$$

θ^2

$$\frac{\chi^2}{2} \approx \frac{\Delta \theta^T \cdot F \cdot \Delta \theta}{2}$$
$$\approx \theta^2 + \dots$$

$\approx \theta^2$

HMC Algorithm

