

بِسْمِ اللَّهِ الرَّحْمَنِ الرَّحِيمِ



Department of Physics

# Morphological properties of Random fields

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# The main goals:

- 1) Morphology
- 2) Assessment of (Phase transition, Anisotropy, Non-Gaussianity, ...);  
Case studies: PTA, RSD, Density fields, Rough surface, ...
- 3) Morphological based analysis
  - To put pristine constraints on the Physical parameters;
  - To use for early warning signal for phase transition;

For more details see:

[1] Mohammad Hossein Jalali and S. M. S. Movahed, "Probing the anisotropy and non-Gaussianity in redshift space through the derivative of excursion set moments", arXiv:2308.03086, submitted to The Astrophysical Journal.

[2] H. Masoomy, S. Tajik, and S. M. S. Movahed, "Homology groups of embedded fractional Brownian motion." *Physical Review E* 106.6 (2022): 064115.

[3] H. Masoomy, B. Askari, M. N. Najafi and S. M. S. Movahed, "Persistent homology of fractional Gaussian noise", *Physical Review E*, 104.3 (2021):034116.

# Outline

## 1) Morphological approaches to examine Stochastic fields

- Geometrical and Topological measures
- Probabilistic and Perturbation frameworks

## 2) Redshift Space (Anisotropy and Non-Gaussianity)

# A glance at the roadmap (1)

**My road map:  
Morphology**

**Underlying Theories** ⊕

**Simulations** ⊕

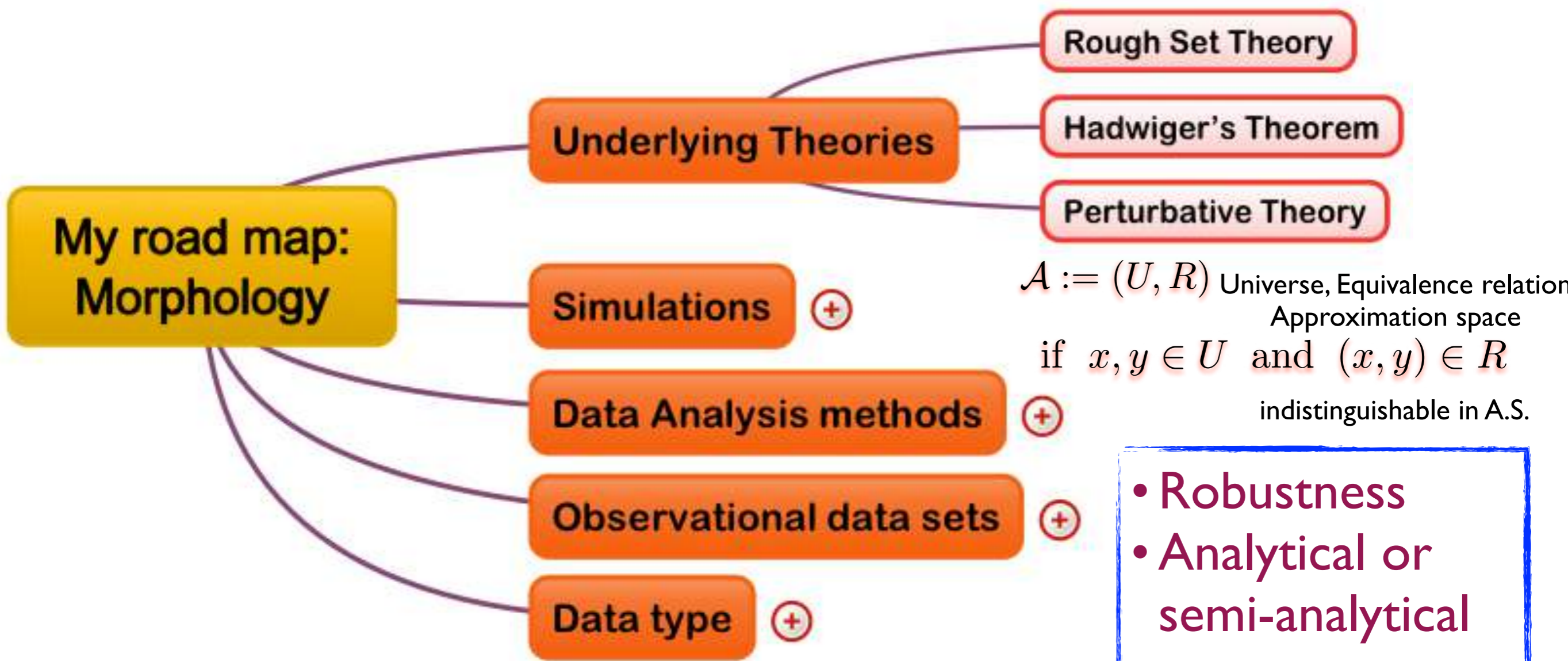
**Data Analysis methods** ⊕

**Observational data sets** ⊕

**Data type** ⊕



# A glance at the roadmap (2)



$A := (U, R)$  Universe, Equivalence relation  
 Approximation space  
 if  $x, y \in U$  and  $(x, y) \in R$   
 indistinguishable in A.S.

- Robustness
- Analytical or semi-analytical measures

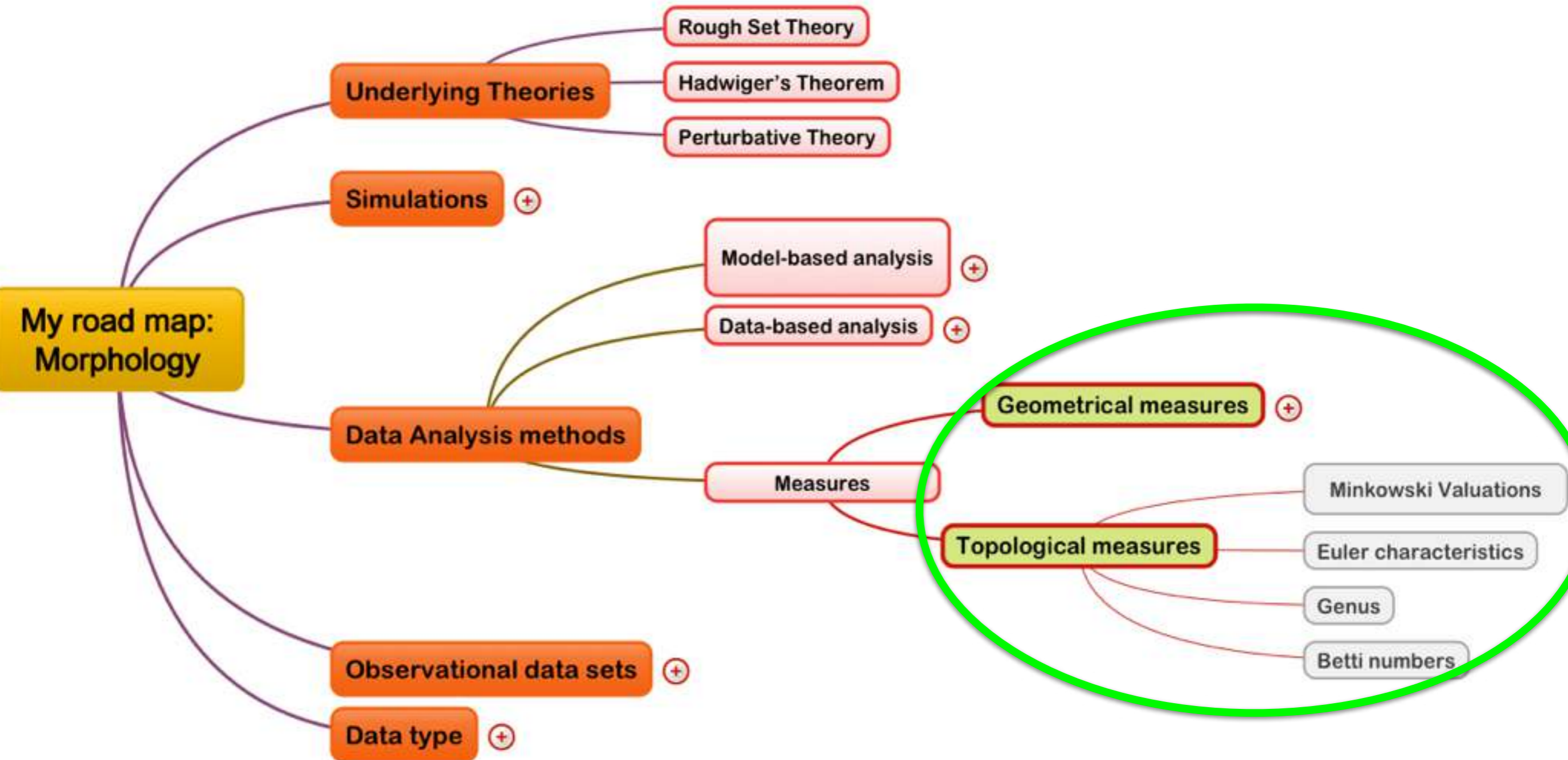
- Motion invariance
- Additivity
- Conditional Continuity

$$M(tB) = M(B) \quad \text{for any } t \in T ; B \in \mathcal{R}$$

$$M(B_1 \cup B_2) = M(B_1) + M(B_2) - M(B_1 \cap B_2) \quad \text{for any } B_1, B_2 \in \mathcal{R}$$

$$M(K_i) \rightarrow M(K) \quad K_i \rightarrow K \quad \text{for } K_i, K \in \mathcal{K}$$

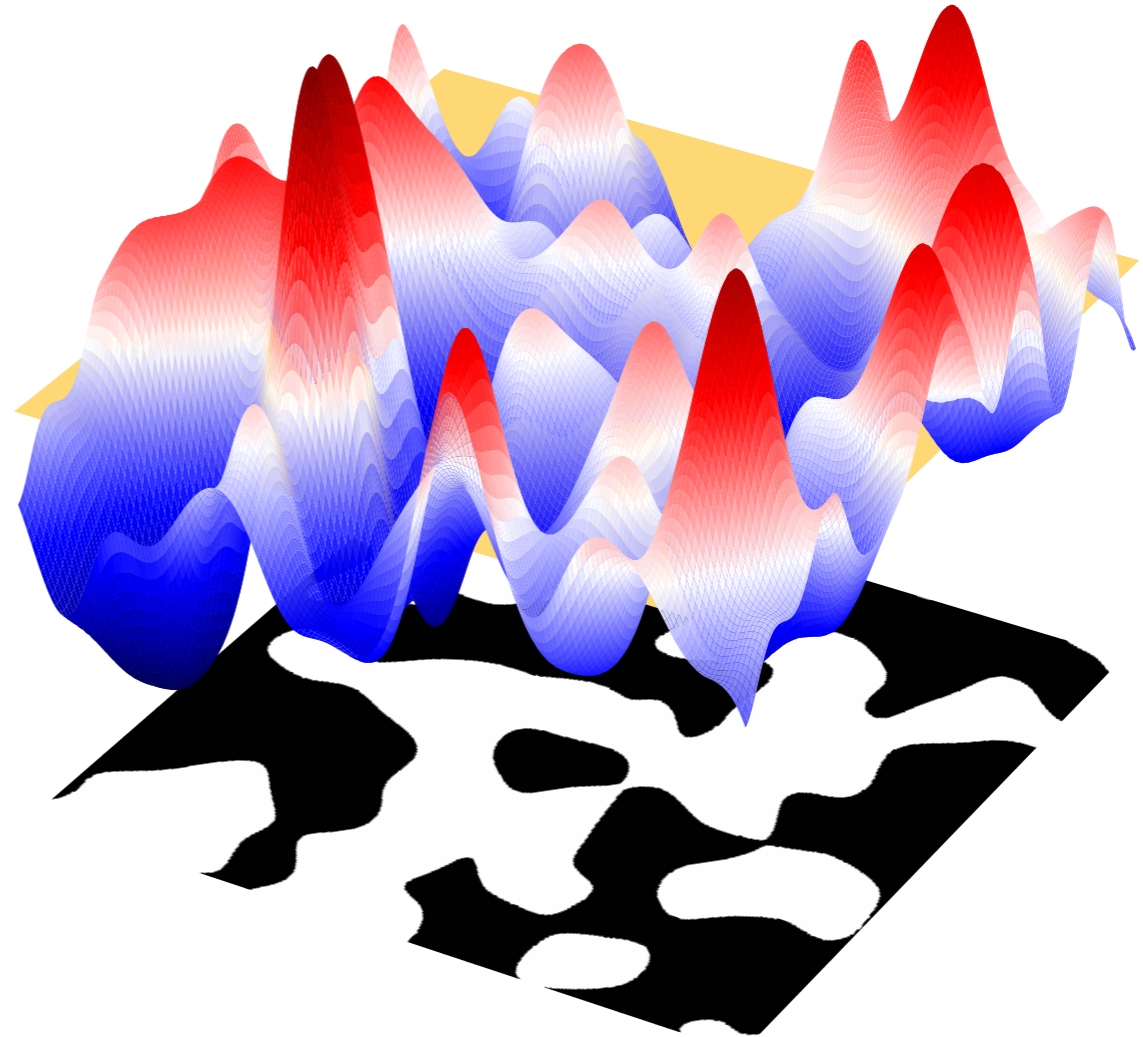
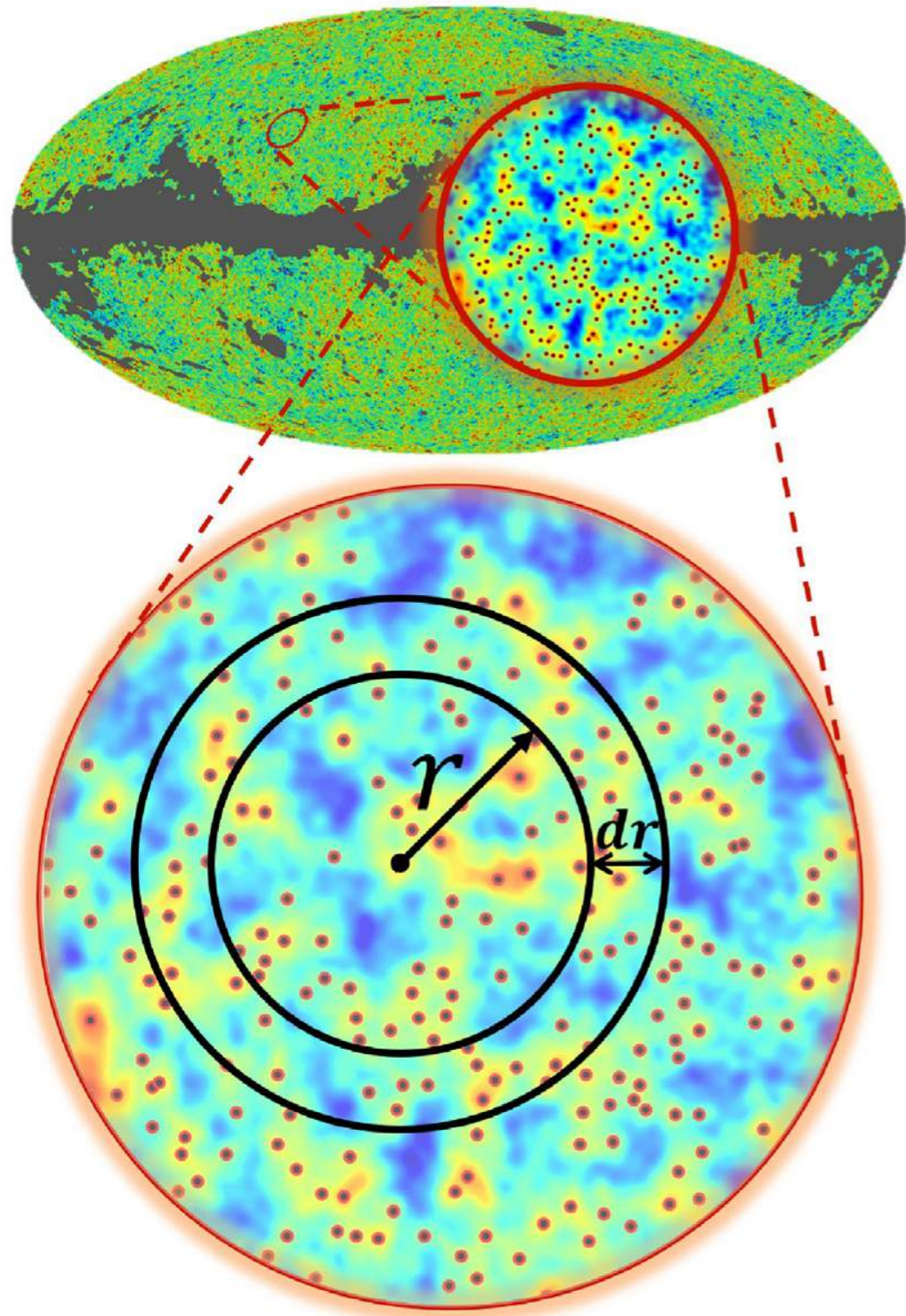
# A glance at the roadmap (3)





# I) Critical Sets

## General features



$$A_\vartheta(\mathcal{F}) \equiv \{X | \mathcal{F}(X) \geq \vartheta\}$$

# 2) Excursion Sets

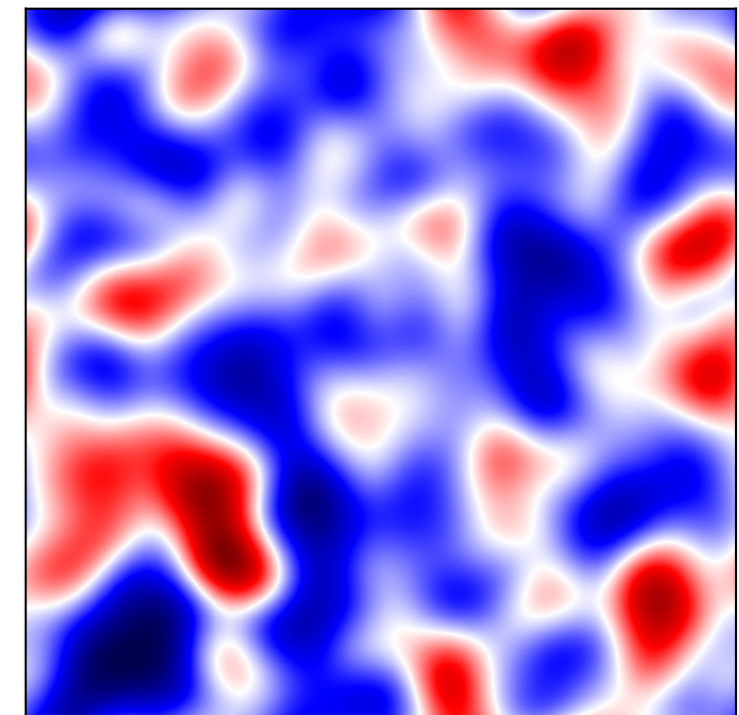
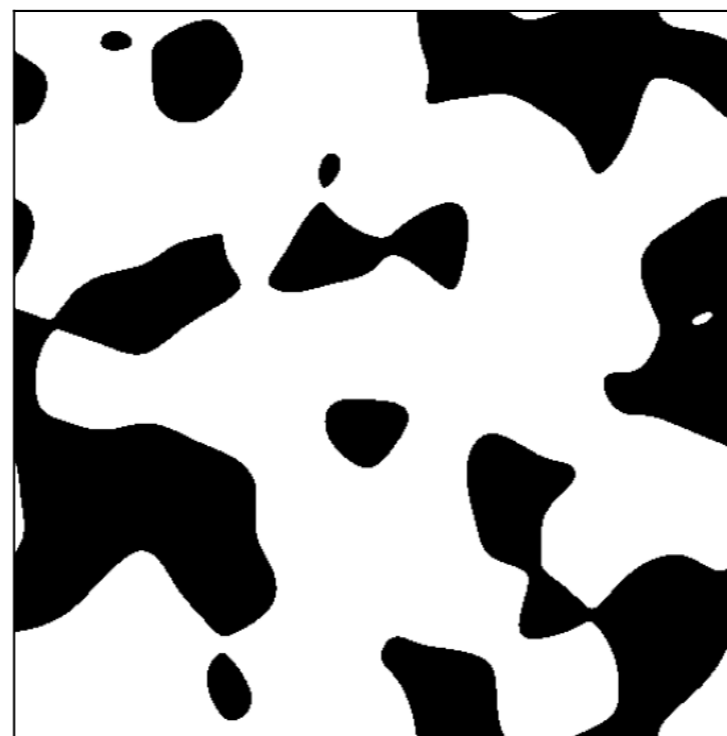
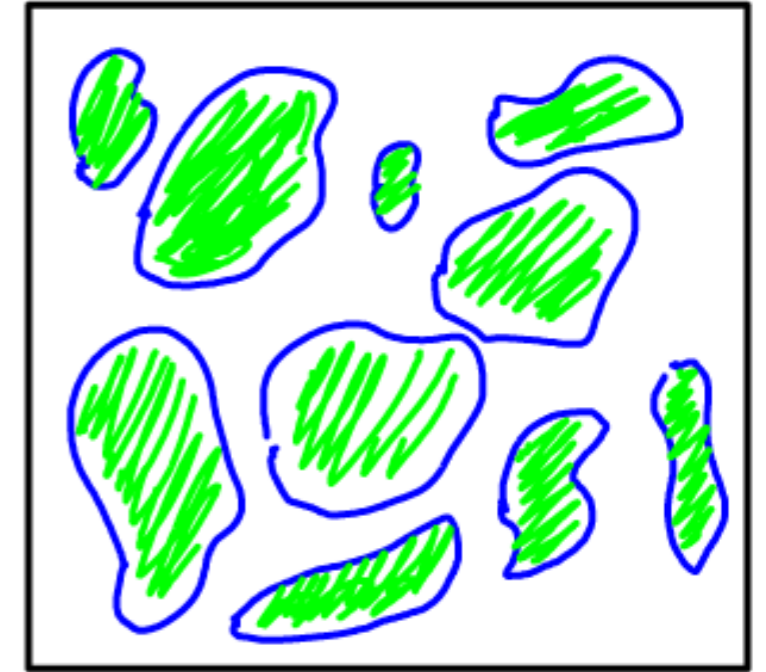
Bardeen, James M., et al., *Astrophysical Journal*, vol. 304, May 1, 1986, p. 15-61.  
Vafaei Sadr, A., and SMSM, *MNRAS* (2021)  
SMSM, B. Javanmardi and R. K. Sheth, *MNRAS*, (2013)

Mohammad Hossein Jalali and SMSM, arXiv:2308.03086,

# Minkowski Functionals (scalar)

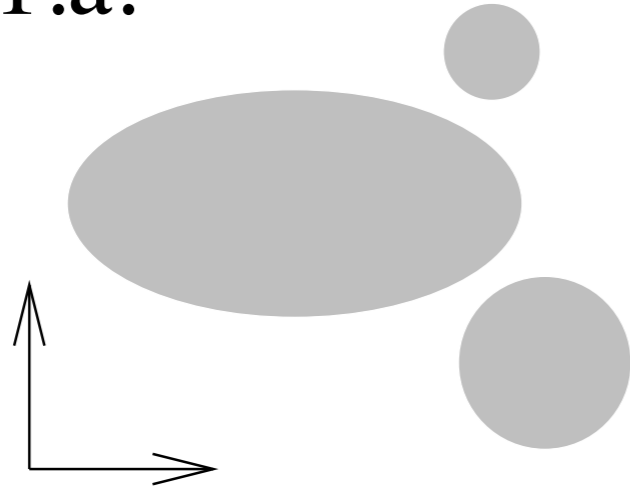
## 2D field

- $V_0(\nu) = \int_{\mathcal{Q}} dA = \langle \theta(\alpha - \nu) \rangle$
- $V_1(\nu) = \frac{1}{4} \int_{\partial \mathcal{Q}} dl = \frac{\pi}{8} \langle \delta_D(\alpha - \nu) |\eta_1| \rangle \sim N_1(\nu)$
- $V_2(\nu) = \frac{1}{2\pi} \int_{\partial \mathcal{Q}} \kappa dl = -\frac{1}{2} \langle \delta_D(\alpha - \nu) \delta_D(\eta_1) |\eta_1| \kappa_{11} \rangle$

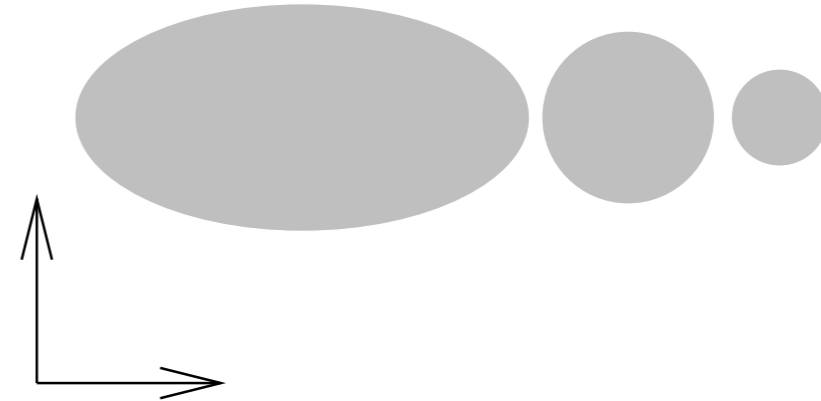


# Generalization of Minkowski Functionals Minkowski Valuations (MVs)

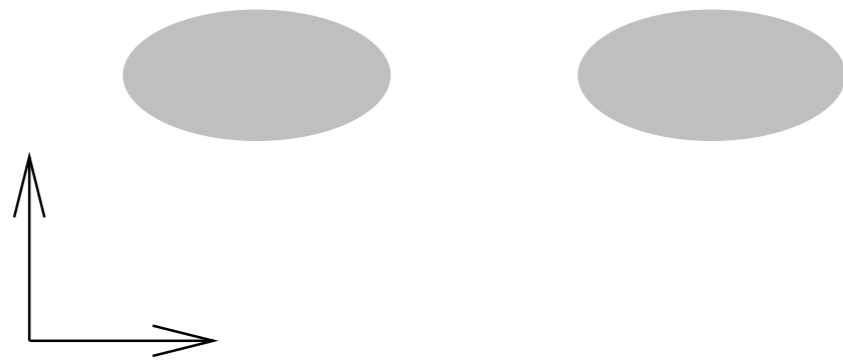
1.a.



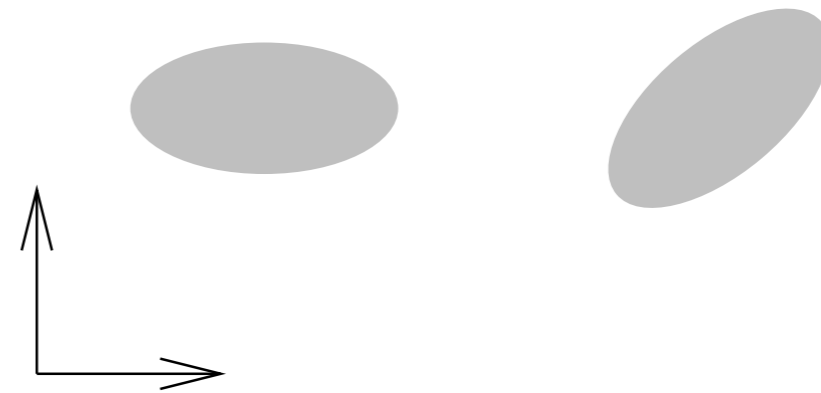
1.b.



2.a.



2.b.

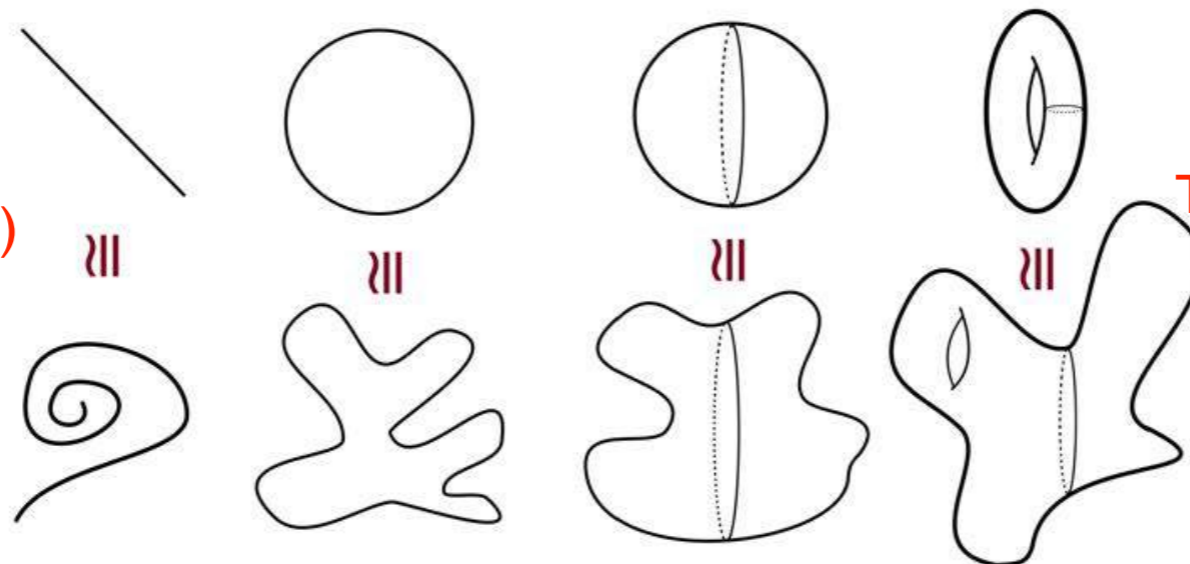




# Topology vs. Geometry



Topological equivalence:  
**Homeomorphism**  
 (Elastic motion:  
 stretch, squeeze, twist, bend)

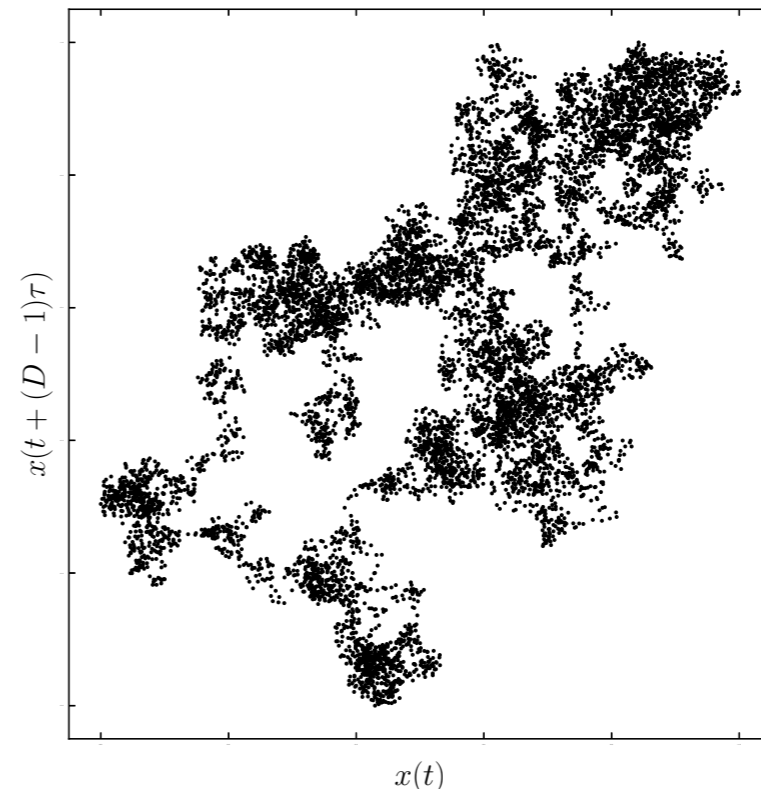
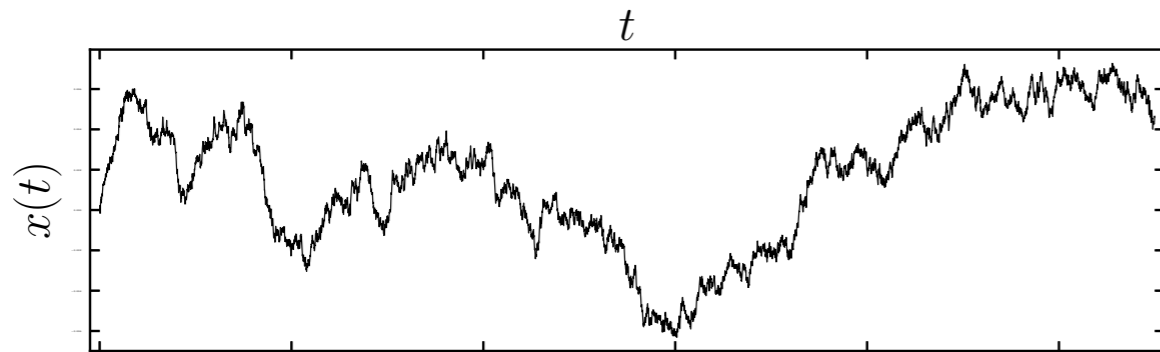
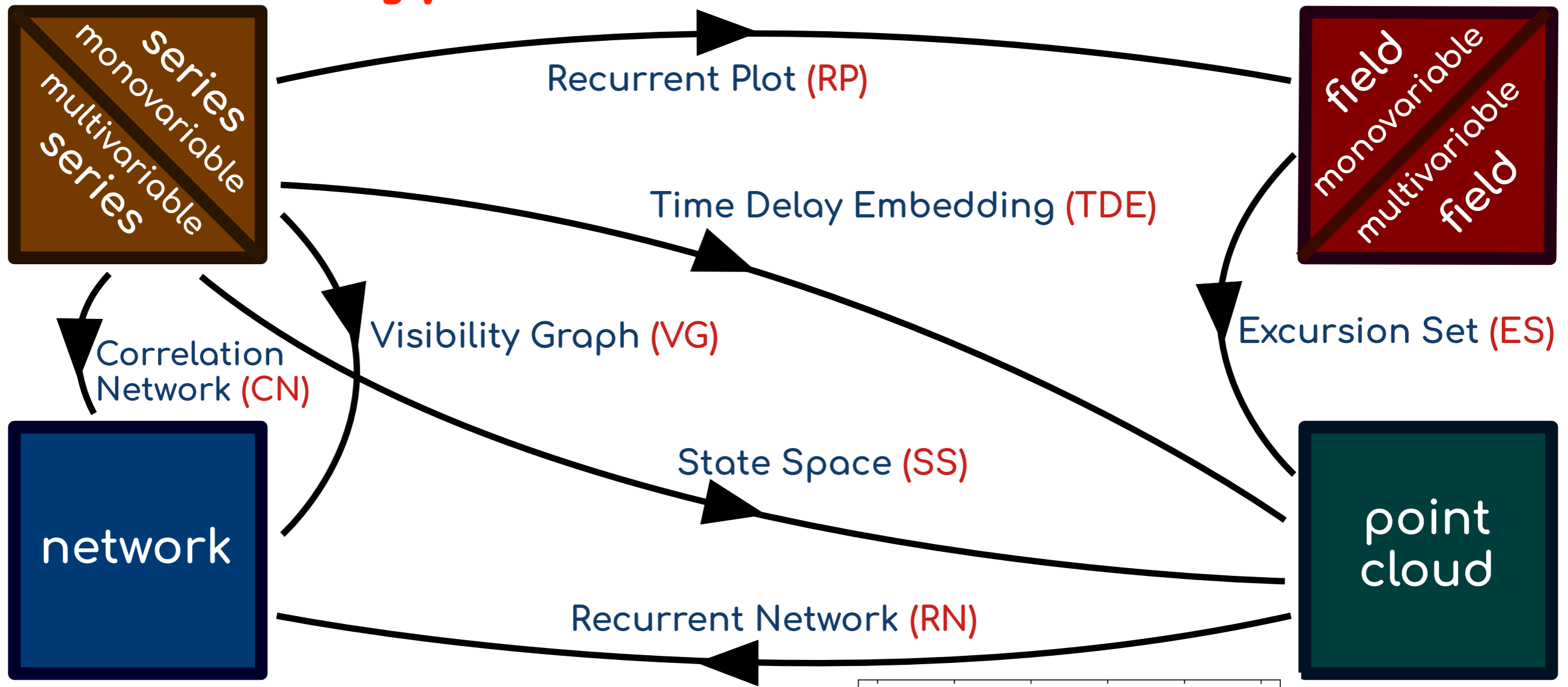


Geometrical equivalence:  
**congruence** (Rigid motion:  
 Transformation, Rotation, Reflection)

Any congruent spaces are topologically homeomorphic, but its inverse is not necessarily true



# Data types and Conversion methods



credit: Hossein Maasoumi, M.Sc.Thesis

To know more visit:  
<http://ccg.sbu.ac.ir/tdaw/>

# Probabilistic frameworks and Theoretical approach

## One-point statistics

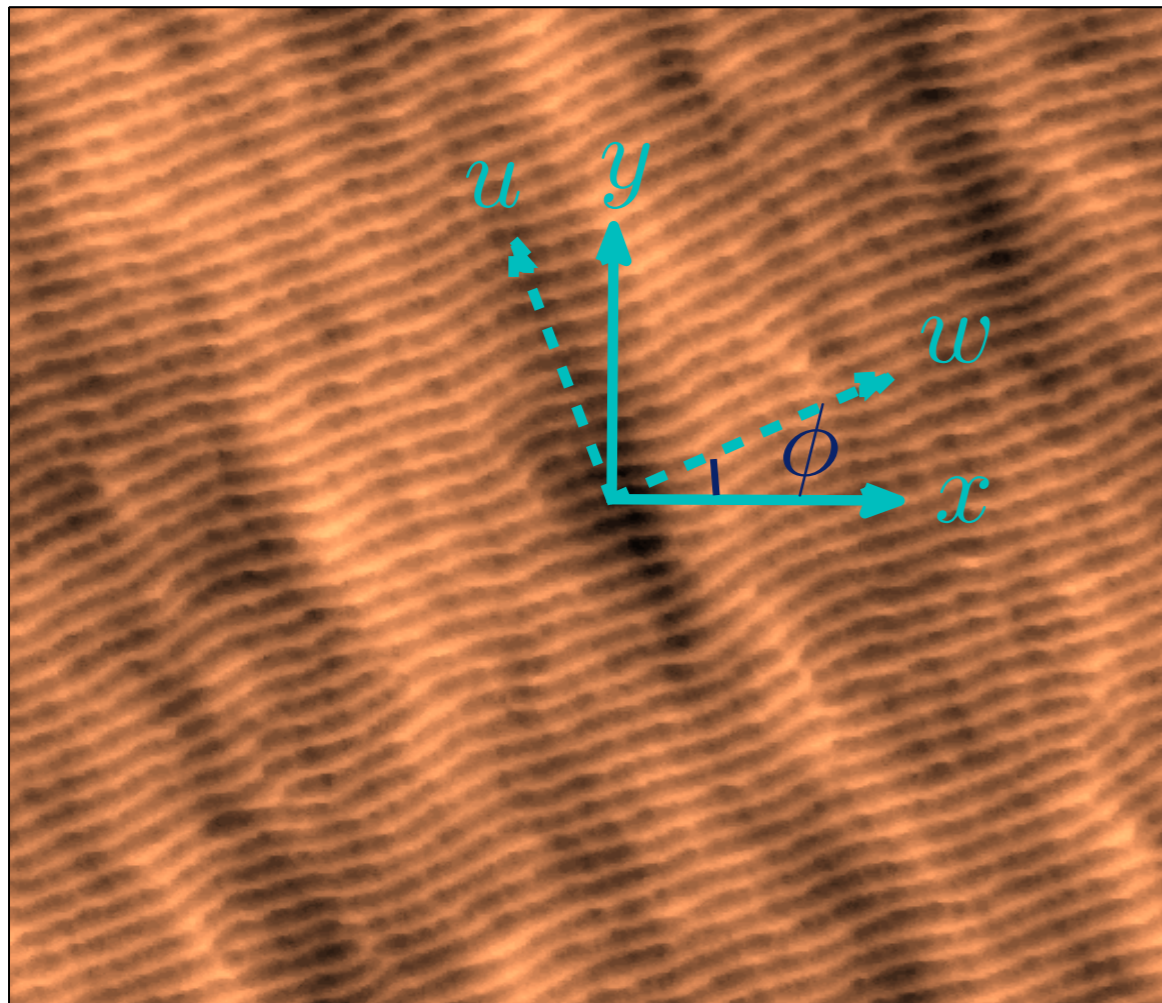
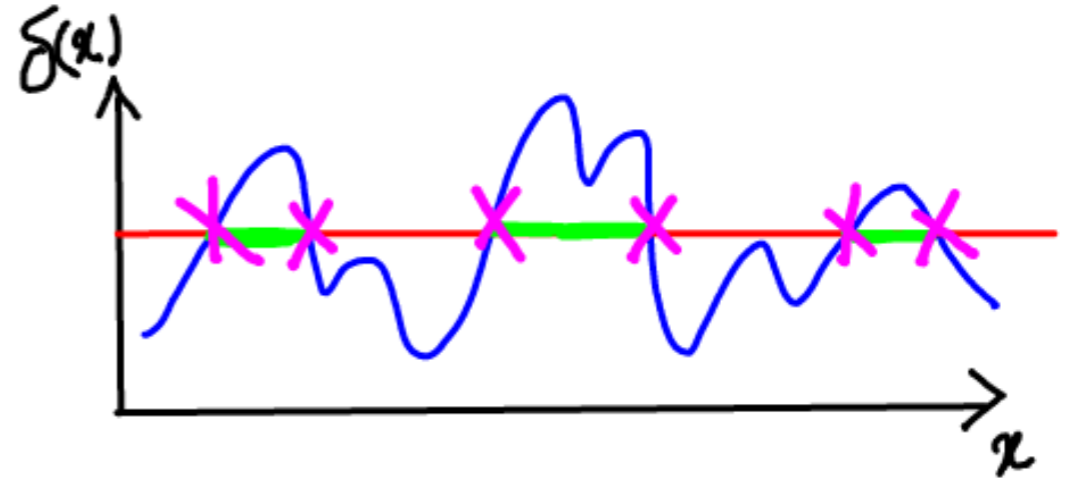
$$\begin{aligned}\langle f \rangle &= \langle \text{Conditions correspond to feature} \rangle \\ &= \langle f \rangle_{\text{Gaussian}} + \text{Perturbative Parts} \Big|_{\text{NG} + \text{Anisotropy}}\end{aligned}$$

## Two-point statistics

$$\begin{aligned}\langle f(r_1) g(r_2) \rangle &= \int dA_1 dA_2 P(A_1, A_2) f(r_1) g(r_2) \\ P(\vec{A}_1, \vec{A}_2) &= \left[ \frac{1}{2\pi^N \text{Det}(K)} \right]^{\frac{1}{2}} \exp\left( - \frac{\vec{A}_1^\dagger \cdot \vec{K}^{-1} \cdot \vec{A}_2}{2} \right)\end{aligned}$$

# Proposed measure

$$N_{cr}^{(r,s)}(\vartheta, i) = \left\langle \delta_D \left( \delta^{(r,s)} - \vartheta \sigma_0^{(r,s)} \right) \left| \delta_{,i}^{(r,s)} \right| \right\rangle$$



Model 1: correlation length anisotropy

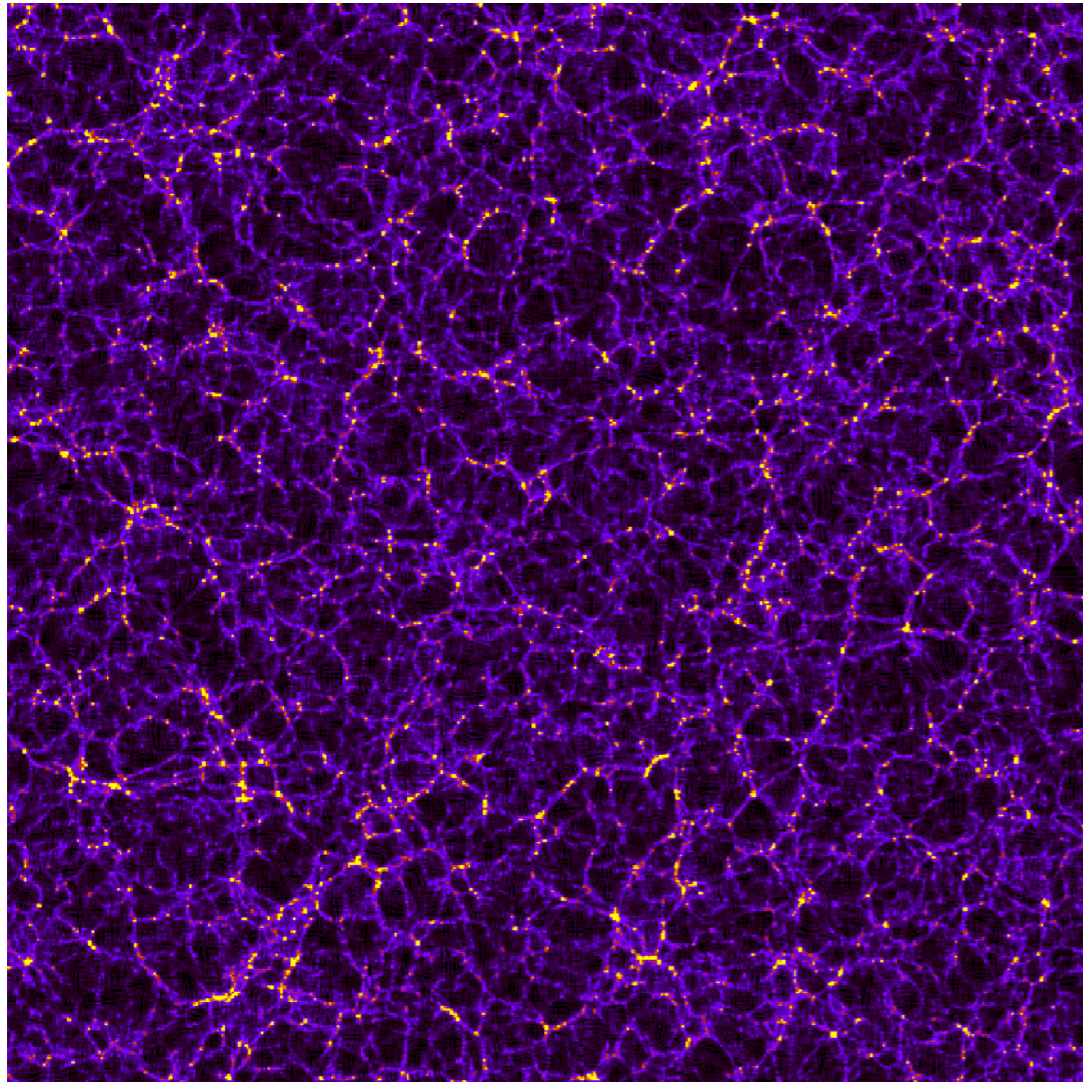
$$S^{(2-D)}(\mathbf{k}) = \frac{4\pi\gamma\sigma_0^2 k_c^{2\gamma} \xi_u \xi_w}{[k_c^2 + \xi_u^2 k_u^2 + \xi_w^2 k_w^2]^{\gamma+1}}$$

Model 2: Scaling anisotropy

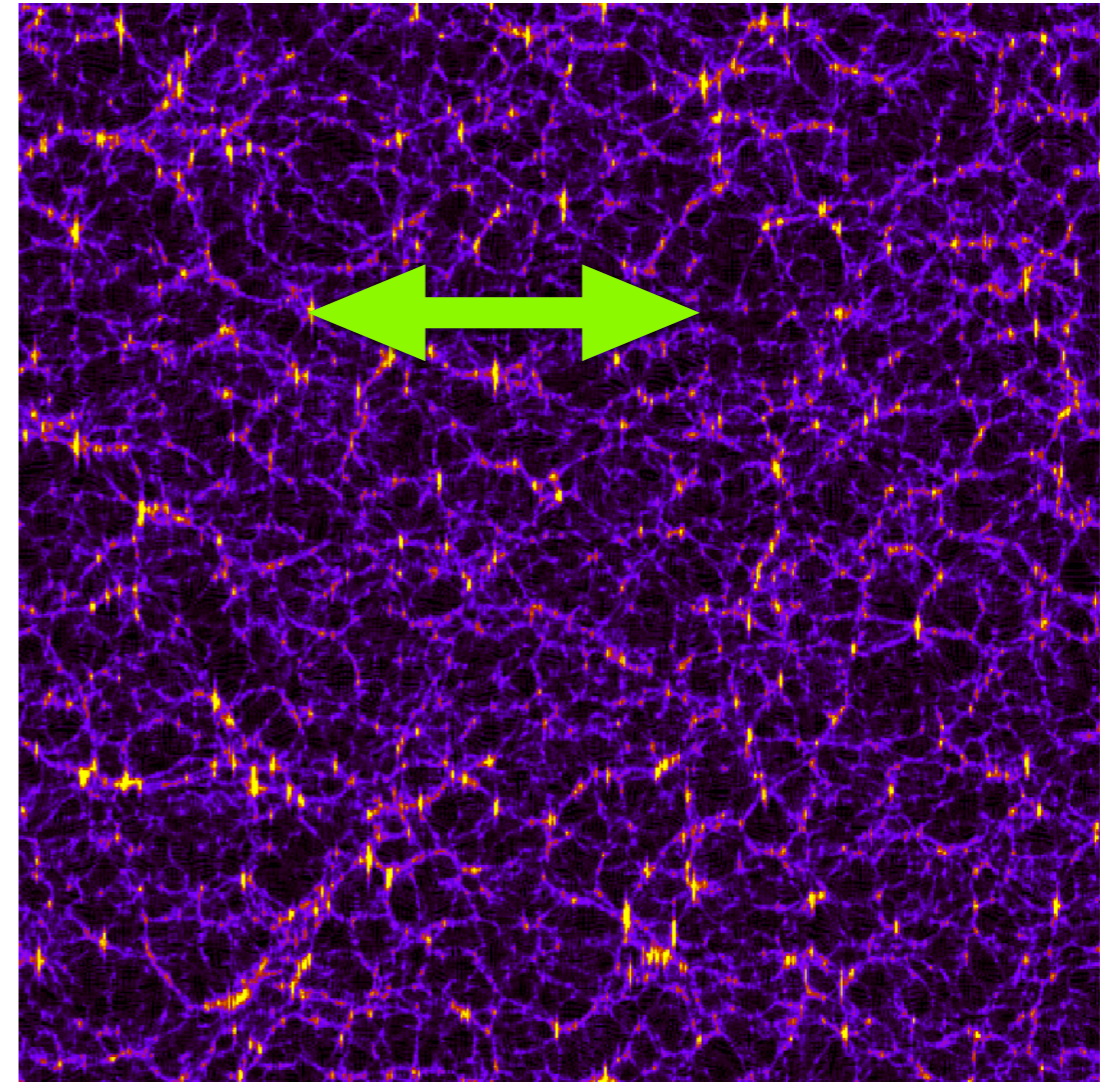
$$S^{(2-D)}(\mathbf{k}) = \frac{4\pi\sigma_0^2 k_c^{2(\gamma_u+\gamma_w)} \xi_u \xi_w \frac{\Gamma(\frac{1}{2}+\gamma_u)}{\Gamma(\gamma_u)} \frac{\Gamma(\frac{1}{2}+\gamma_w)}{\Gamma(\gamma_w)}}{[k_c^2 + \xi_u^2 k_u^2]^{\gamma_u+1/2} [k_c^2 + \xi_w^2 k_w^2]^{\gamma_w+1/2}}$$



# RSD: Linear Kaiser effect

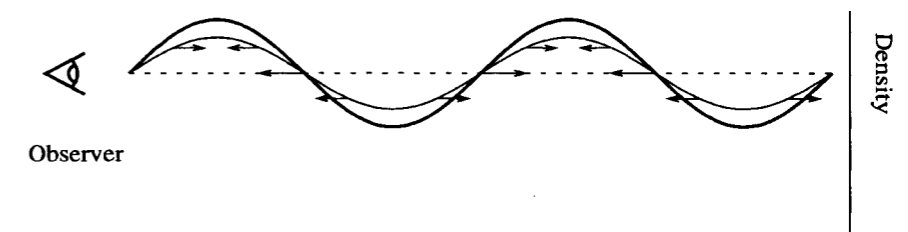


Without RSD



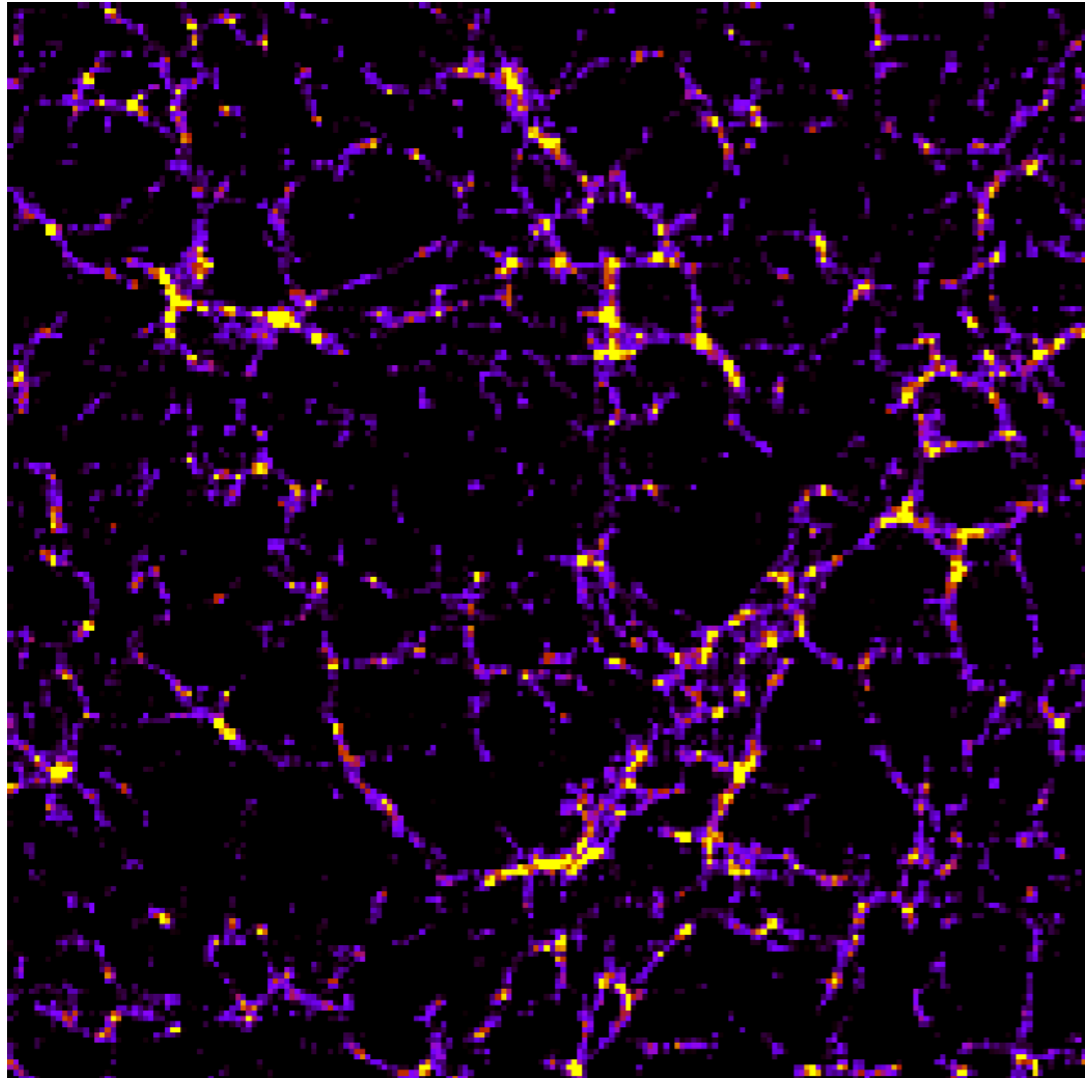
With RSD

↑  
Line of sight

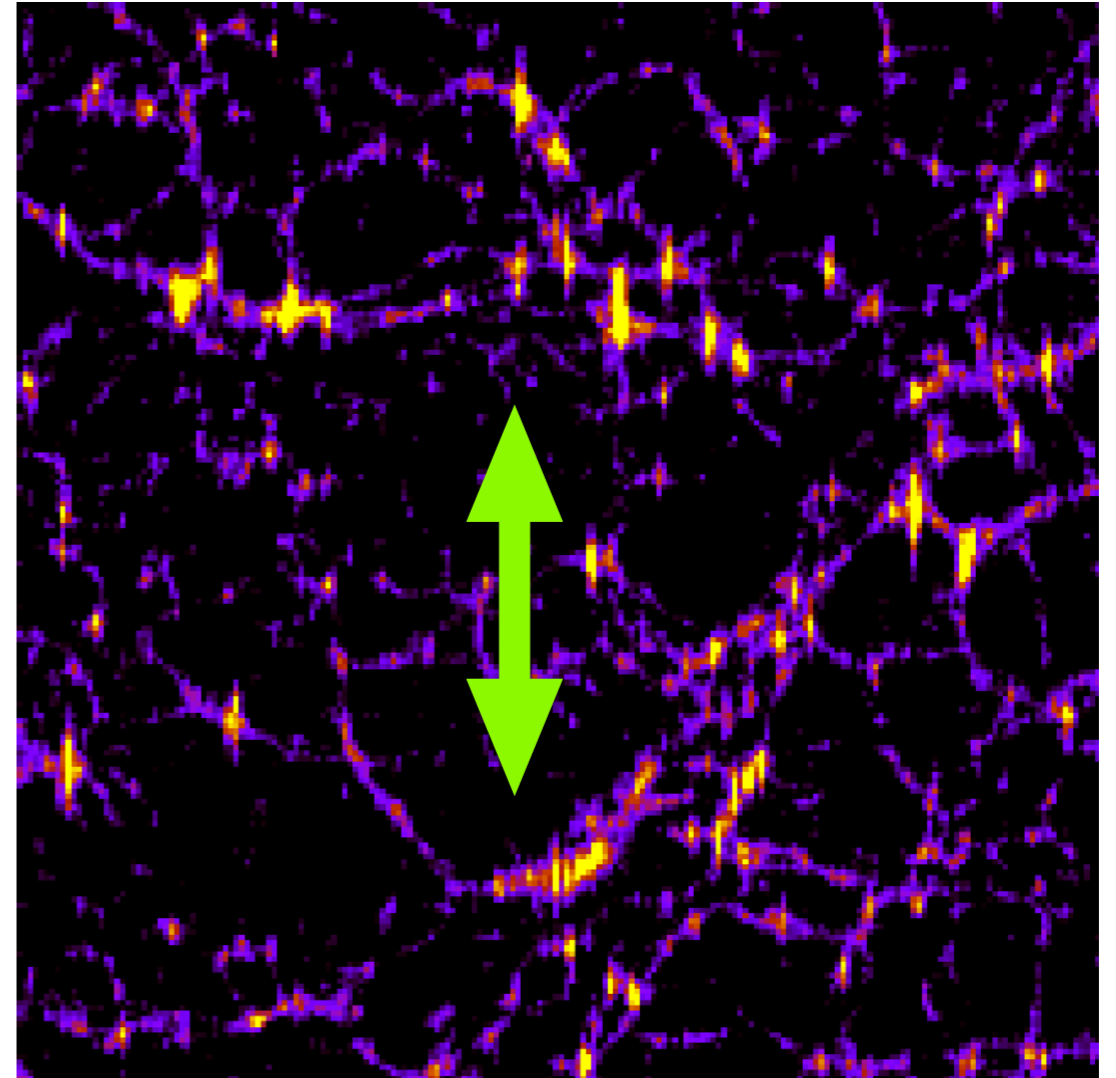




# FoG effect



Without RSD



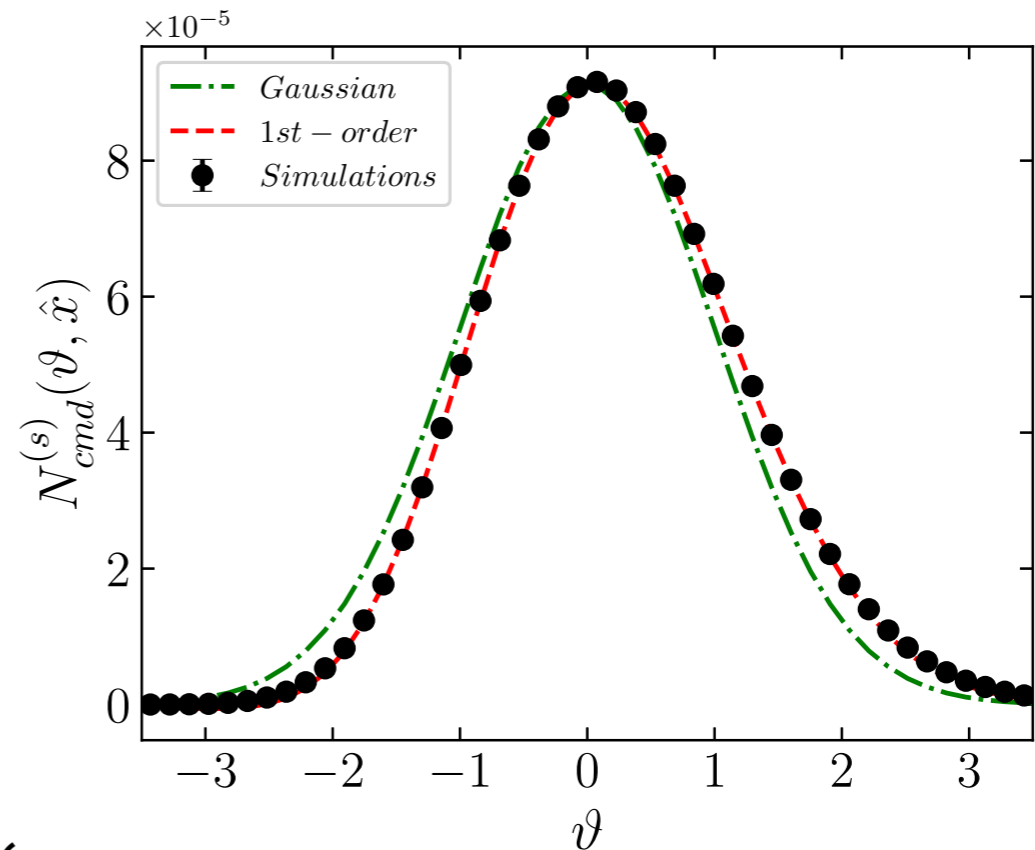
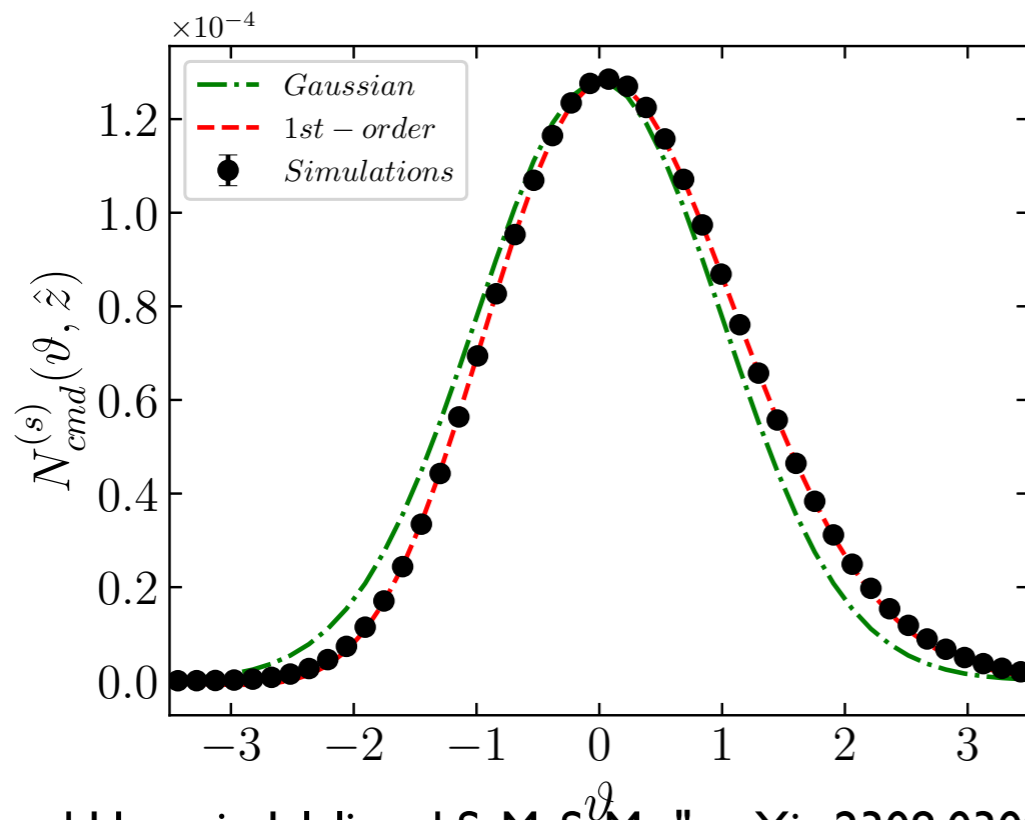
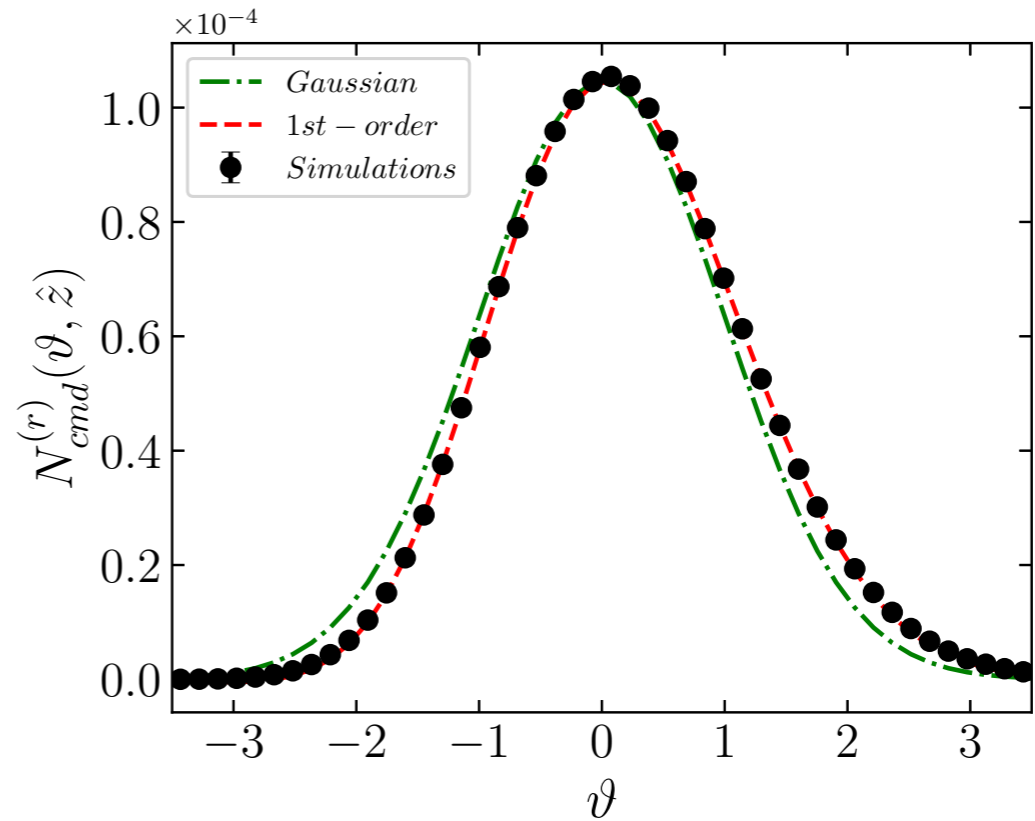
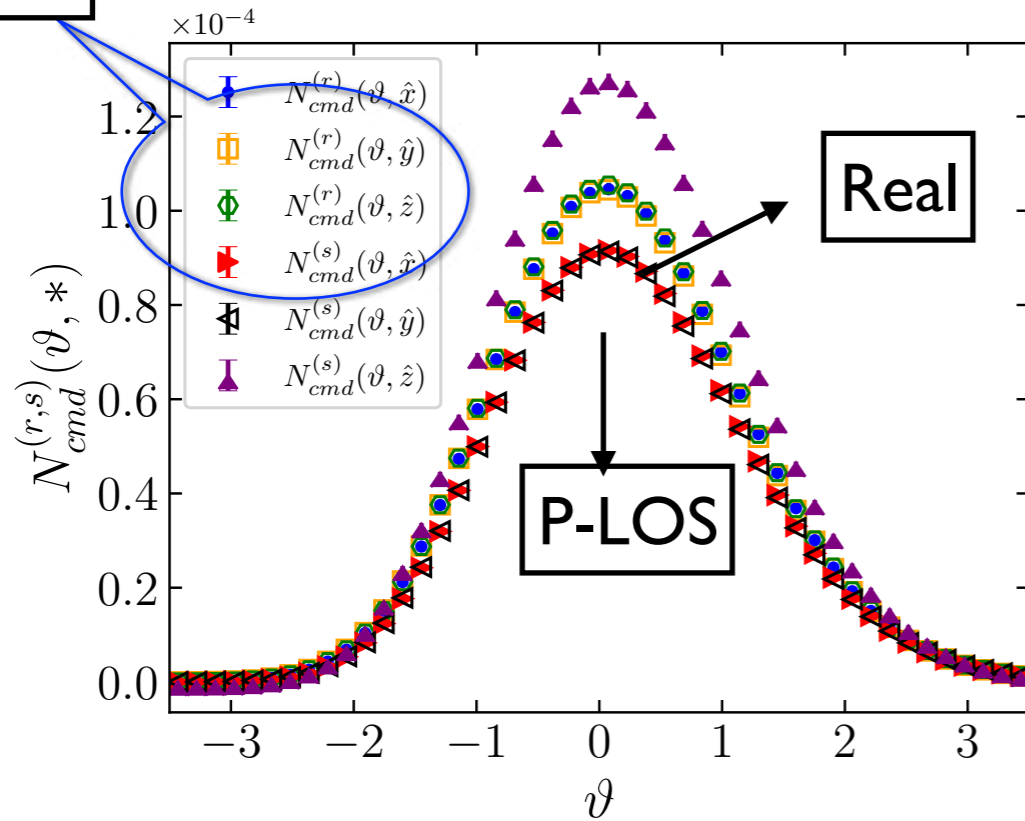
With RSD



Line of sight

# Quijote N-body simulation

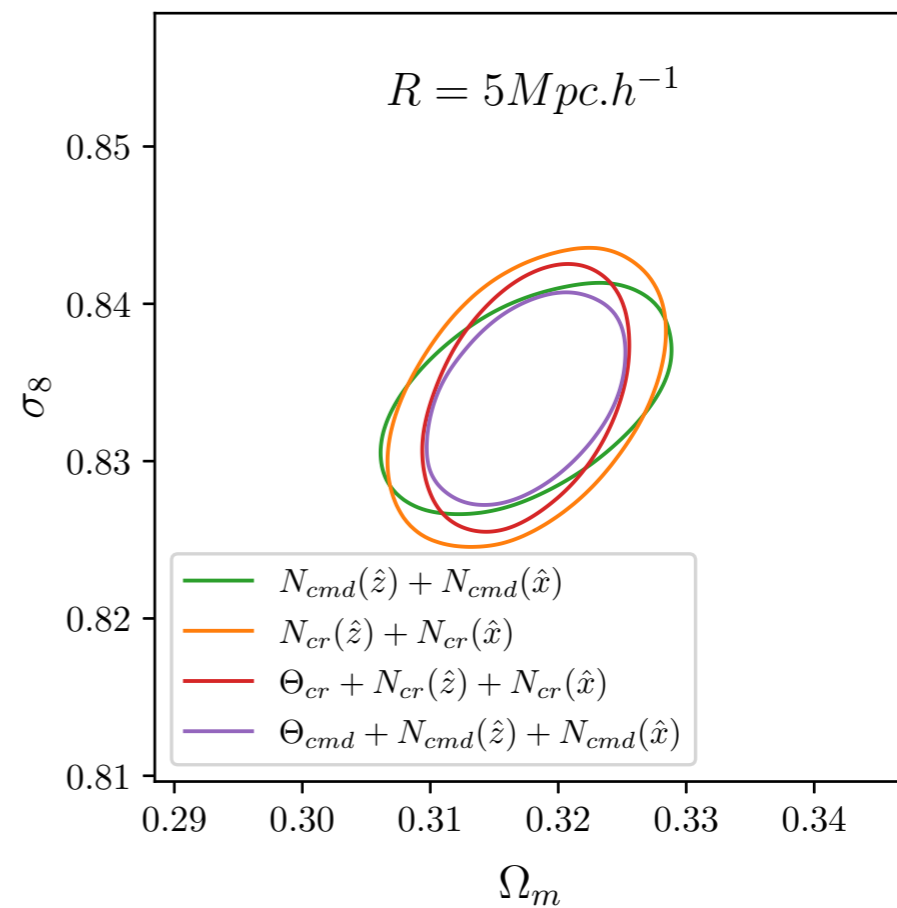
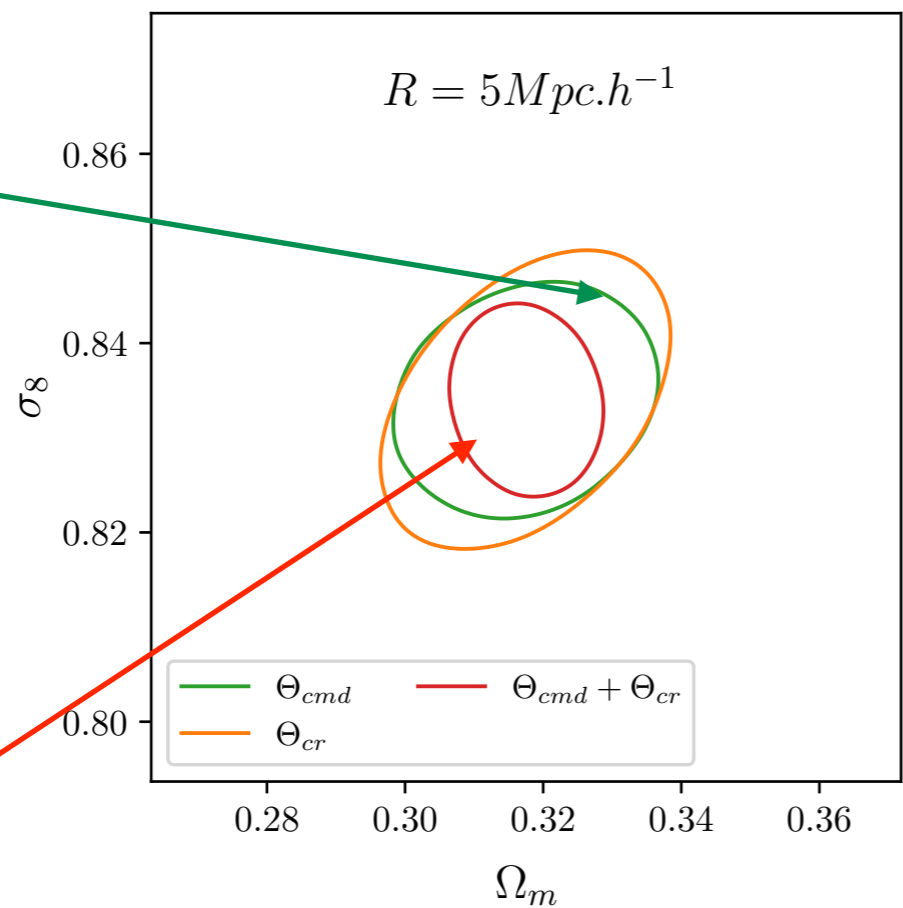
Real



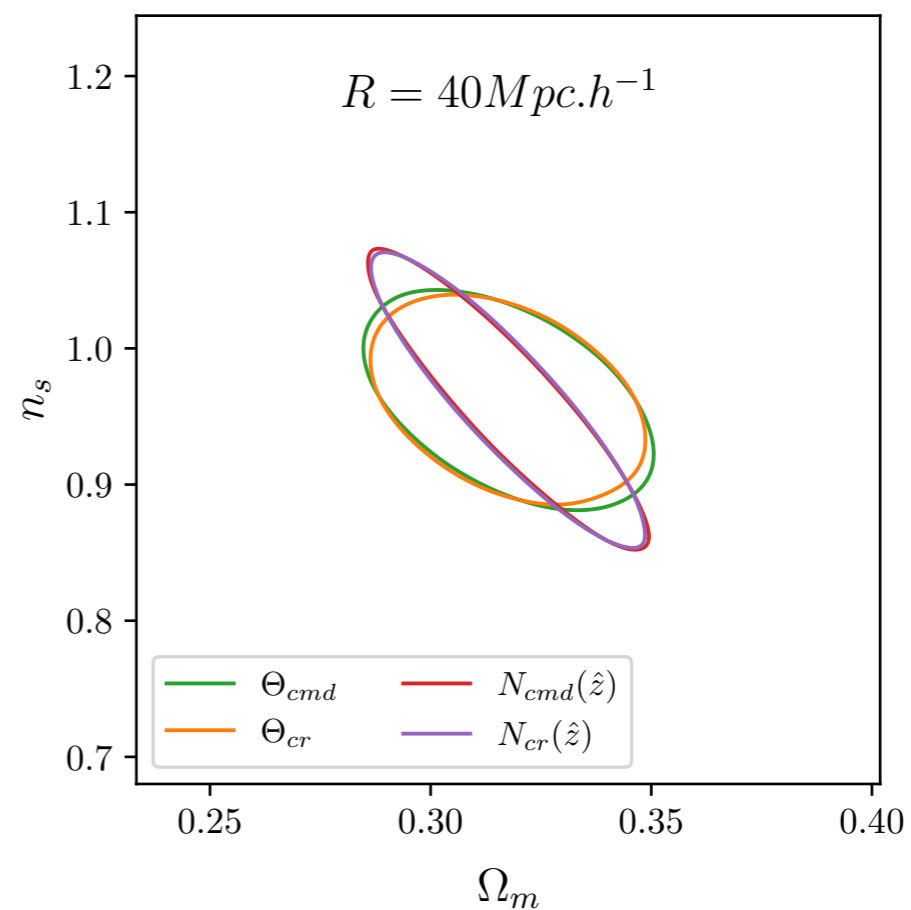
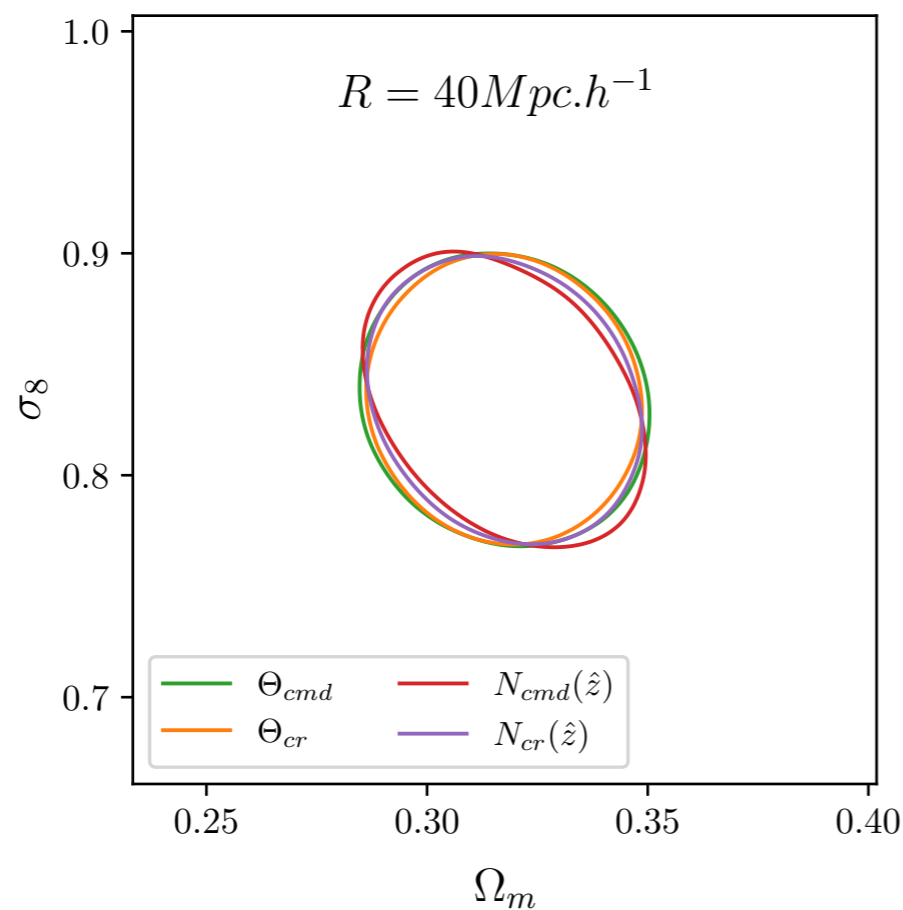


$\Theta_{cmd}$   
 $\sim 10\% \Omega_m$   
 $\sim 20\% \sigma_8$

$\Theta_{cmd} + \Theta_{cr}$   
 $45\% \Omega_m$   
 $35\% \sigma_8$



Reducing degeneracy



# Concluding remarks and Take-Home messages

- 1) Morphologies contain valuable information, particularly in the high-precision data era;
- 2) Reducing the degeneracies via data-based modeling;
- 3) Put pristine constraints on relevant parameters;

# What the next?

- 1) Construction new measures
- 2) Beyond Plane-Parallel approximation.
- 3) Various field (Finding preferred direction) + Moving window + Iterative Coarse Graining
- 4) Making a pipeline including various measures ranging from geometry to topology and utilizing Machine learning







# Stochastic fields, Stochastic processes, Random fields

## 1) Measure-theoretic definition (probability triple)

Probability space (probability triple) is represented by  $(\Omega, \mathcal{F}, \mathbb{P})$

$\Omega$  is sample space. It contains all possible outcomes

$\mathcal{F}$  is event space ( $\sigma$ -algebra)

A probability function ( $0 \leq \mathbb{P} \leq 1$ ), assigns a probability to each event in the event space

$$\{\Omega, \mathcal{F}, \mathbb{P}\}$$

Just one flip of Fair coin

$$\Omega = \{Heads, Tails\} \equiv \{\mathbf{H}, \mathbf{T}\}$$

$$\mathcal{F} = \{\{\}, \{\mathbf{H}\}, \{\mathbf{T}\}, \{\mathbf{H}, \mathbf{T}\}\}$$

$$\mathbb{P}(\{\}) = 0; \mathbb{P}(\{\mathbf{H}\}) = 0.5; \mathbb{P}(\{\mathbf{T}\}) = 0.5; \mathbb{P}(\{\mathbf{H}, \mathbf{T}\}) = 1$$

$$f^d : \Omega \rightarrow \mathbb{R}^T$$

$$T \subset \mathbb{R}^N$$

$f$  is a  $(d + N)$  – Dimensional Stochastic field

## 2) Probabilistic framework definition

$X(t, \omega)$  is stochastic variable

$$\mathbb{P}\{X(t_1), X(t_2), \dots, X(t_m)\}$$

# Probability space

Probability space (probability triple) is represented by  $(\Omega, \mathcal{F}, \mathbb{P})$

$\Omega$  is sample space. It contains all possible outcomes

$\mathcal{F}$  is event space ( $\sigma$ -algebra)

A probability function ( $0 \leq \mathbb{P} \leq 1$ ), assigns a probability to each event in the event space

## Example 1:

Just one flip of Fair coin

$$\Omega = \{Heads, Tails\} \equiv \{\mathbf{H}, \mathbf{T}\}$$

$$\mathcal{F} = \{\{\}, \{\mathbf{H}\}, \{\mathbf{T}\}, \{\mathbf{H}, \mathbf{T}\}\}$$

$$\mathbb{P}(\{\}) = 0; \mathbb{P}(\{\mathbf{H}\}) = 0.5; \mathbb{P}(\{\mathbf{T}\}) = 0.5; \mathbb{P}(\{\mathbf{H}, \mathbf{T}\}) = 1$$

## Example 2:

The fair coin is tossed three times.

$$\Omega = \mathbf{HHH}, \mathbf{HHT}, \mathbf{HTH}, \mathbf{HTT}, \mathbf{THH}, \mathbf{THT}, \mathbf{TTH}, \mathbf{TTT}$$

$$\mathcal{F} = 2^{|\Omega|} = 2^8 = 256$$