

Answer to Exercise set 6

1&3. We answer question 1 and 3 together. We have:

$$P(x, t|x', t') = e^{\int L_{KM}(x,t)dt} \delta(x - x')$$

for $\tau = t - t' \ll 1$ we can expand above so:

$$P(x, t + \tau|x', t) = [1 + L_{KM}(x, t)\tau + \mathcal{O}(\tau^2)]\delta(x - x') \quad (1)$$

We know Keramers-Moyal coefficient bigger than 3 is zero so:

$$P(x, t + \tau|x', t) = [1 + L_{FP}(x, t)\tau + \mathcal{O}(\tau^2)]\delta(x - x')$$

and:

$$L_{FP} = -\frac{\partial}{\partial x}D^{(1)}(x, t) + \frac{\partial^2}{\partial x^2}D^{(2)}(x, t)$$

Plugin above expression in 1 we obtain:

$$\begin{aligned} P(x, t + \tau|x', t) &= [1 - \frac{\partial}{\partial x}D^{(1)}(x, t)\tau + \frac{\partial^2}{\partial x^2}D^{(2)}(x, t)\tau]\delta(x - x') \\ &= \exp \left[-\frac{\partial}{\partial x}D^{(1)}(x, t)\tau + \frac{\partial^2}{\partial x^2}D^{(2)}(x, t)\tau \right] \delta(x - x') \\ &\stackrel{1}{=} \exp \left[-\frac{\partial}{\partial x}D^{(1)}(x', t)\tau + \frac{\partial^2}{\partial x^2}D^{(2)}(x', t)\tau \right] \delta(x - x') \end{aligned} \quad (2)$$

We use the Fourier transform of the delta function, so:

$$\begin{aligned} P(x, t + \tau|x', t) &= \exp \left[-\frac{\partial}{\partial x}D^{(1)}(x', t)\tau + \frac{\partial^2}{\partial x^2}D^{(2)}(x', t)\tau \right] \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{iu(x-x')} du \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \exp \left[-iuD^{(1)}(x', t) - u^2D^{(2)}(x', t)\tau + iu(x - x') \right] du \\ &= \frac{1}{2\sqrt{\pi D^{(2)}(x', t)\tau}} \exp \left(-\frac{[x - x' - D^{(1)}(x', t)\tau]^2}{4D^{(2)}(x', t)\tau} \right) \end{aligned} \quad (3)$$

We find the answer of the Ex#3 part a.

Conditional moments are defined as below:

$$M_n(x', t, \tau) = \int (x - x')^n P(x, t + \tau|x', t) dx$$

¹ We can replace x, x' because of $\delta(x - x')f(x') = \delta(x - x')f(x)$

We put 3 and change of variable like $\alpha = \frac{x-x'}{2\sqrt{D^{(2)}(x',t)\tau}}$ we can calculate integral and we get:

$$\begin{aligned}
M_n(x', t, \tau) &= \frac{\left[2\sqrt{D^{(2)}(x', t)\tau}\right]^{n+1}}{2\sqrt{\pi}D^{(2)}(x', t)\tau} \int \alpha^n \exp\left(-\left[\alpha - \frac{D^{(1)}(x', t)\tau}{2\sqrt{D^{(2)}(x', t)\tau}}\right]^2\right) d\alpha \\
&= \left[2\sqrt{D^{(2)}(x', t)\tau}\right]^n \frac{1}{\sqrt{\pi}} \int \alpha^n \exp\left(-\left[\alpha - \frac{D^{(1)}(x', t)\tau}{2\sqrt{D^{(2)}(x', t)\tau}}\right]^2\right) d\alpha \\
&= \left[2\sqrt{D^{(2)}(x', t)\tau}\right]^n \frac{1}{\sqrt{\pi}} (2i)^{-n} \sqrt{\pi} H_n\left\{i \frac{D^{(1)}(x', t)\tau}{2\sqrt{D^{(2)}(x', t)\tau}}\right\} \\
&= \left[-i\sqrt{D^{(2)}(x', t)\tau}\right]^n H_n\left\{\frac{1}{2}iD^{(1)}(x', t)\sqrt{\tau/D^{(2)}(x', t)}\right\}
\end{aligned}$$

Above is answer to Ex#1. We can check our result with below calculation:

$$\begin{aligned}
D^{(1)}(x', t) &= \lim_{\tau \rightarrow 0} \frac{M_1(x', t, \tau)}{\tau} = \lim_{\tau \rightarrow 0} \frac{1}{\tau} \left[-i\sqrt{D^{(2)}(x', t)\tau}\right] H_1\left\{\frac{1}{2}iD^{(1)}(x', t)\sqrt{\tau/D^{(2)}(x', t)}\right\} \\
&= \lim_{\tau \rightarrow 0} \frac{1}{\tau} \left[-i\sqrt{D^{(2)}(x', t)\tau}\right] 2\left(\frac{1}{2}iD^{(1)}(x', t)\sqrt{\tau/D^{(2)}(x', t)}\right) \\
&= \lim_{\tau \rightarrow 0} \frac{\tau}{\tau} D^{(1)}(x', t) = D^{(1)}(x', t) \quad \checkmark
\end{aligned}$$

$$\begin{aligned}
D^{(2)}(x', t) &= \lim_{\tau \rightarrow 0} \frac{M_2(x', t, \tau)}{2!\tau} = \lim_{\tau \rightarrow 0} \frac{1}{2\tau} \left[-i\sqrt{D^{(2)}(x', t)\tau}\right]^2 H_2\left\{\frac{1}{2}iD^{(1)}(x', t)\sqrt{\tau/D^{(2)}(x', t)}\right\} \\
&= \lim_{\tau \rightarrow 0} \frac{1}{2\tau} \left[-i\sqrt{D^{(2)}(x', t)\tau}\right]^2 \left(-\left[D^{(1)}(x', t)\sqrt{\tau/D^{(2)}(x', t)}\right]^2 - 2\right) \\
&= \lim_{\tau \rightarrow 0} \frac{1}{2\tau} \left[-D^{(2)}(x', t)\tau\right] \left(-\left[D^{(1)}(x', t)\right]^2 \tau/D^{(2)}(x', t) - 2\right) \\
&= \lim_{\tau \rightarrow 0} \frac{1}{2\tau} \left[-D^{(2)}(x', t)\tau\right] (-2 + \mathcal{O}(\tau^2)) \\
&= D^{(2)}(x', t) \quad \checkmark
\end{aligned}$$

$$\begin{aligned}
D^{(3)}(x', t) &= \lim_{\tau \rightarrow 0} \frac{M_3(x', t, \tau)}{3!\tau} = \lim_{\tau \rightarrow 0} \frac{1}{6\tau} \left[-i\sqrt{D^{(2)}(x', t)\tau}\right]^3 H_3\left\{\frac{1}{2}iD^{(1)}(x', t)\sqrt{\tau/D^{(2)}(x', t)}\right\} \\
&= \lim_{\tau \rightarrow 0} \frac{1}{6\tau} \left[-i\sqrt{D^{(2)}(x', t)\tau}\right]^3 \\
&\quad \times \left(8\left(\frac{1}{2}iD^{(1)}(x', t)\sqrt{\tau/D^{(2)}(x', t)}\right)^3 - 12\left(\frac{1}{2}iD^{(1)}(x', t)\sqrt{\tau/D^{(2)}(x', t)}\right)\right) \\
&= \lim_{\tau \rightarrow 0} \frac{1}{\tau} \mathcal{O}(\tau^{3/2}) \left[\mathcal{O}(\tau^{3/2}) - \mathcal{O}(\tau^{1/2})\right] \\
&= \lim_{\tau \rightarrow 0} \left[\mathcal{O}(\tau^2) - \mathcal{O}(\tau)\right] \\
&= 0 \quad \checkmark
\end{aligned}$$

² Here, we use helpful hint in notebook:

$$\int_{-\infty}^{\infty} x^n e^{-(x-\beta)^2} dx = (2i)^{-n} \sqrt{\pi} H_n(i\beta)$$

We can see that $D^{(3)}(x', t) = 0$, we know from Pawula theorem that all Keramers-Moyal coeffs bigger than 3 are zero and this is completely consistence with Fokker-Planck, Keramers-Moyal coeffs. But this answer are not unique, we can write differential form of Fokker-Planck operator as below:

$$\begin{aligned}
L_{FP}(x, t)\mathcal{F} &= -\frac{\partial}{\partial x} \left(D^{(1)}(x, t)\mathcal{F} \right) + \frac{\partial^2}{\partial x^2} \left(D^{(2)}(x, t)\mathcal{F} \right) \\
&= -\mathcal{F} \frac{\partial D^{(1)}(x, t)}{\partial x} - D^{(1)}(x, t) \frac{\partial \mathcal{F}}{\partial x} + \frac{\partial}{\partial x} \left(\mathcal{F} \frac{\partial D^{(2)}(x, t)}{\partial x} + D^{(2)}(x, t) \frac{\partial \mathcal{F}}{\partial x} \right) \\
&= -\mathcal{F} \frac{\partial D^{(1)}(x, t)}{\partial x} - D^{(1)}(x, t) \frac{\partial \mathcal{F}}{\partial x} + \frac{\partial \mathcal{F}}{\partial x} \frac{\partial D^{(2)}(x, t)}{\partial x} + \mathcal{F} \frac{\partial^2 D^{(2)}(x, t)}{\partial x^2} \\
&\quad + \frac{\partial D^{(2)}(x, t)}{\partial x} \frac{\partial \mathcal{F}}{\partial x} + D^{(2)}(x, t) \frac{\partial^2 \mathcal{F}}{\partial x^2}
\end{aligned}$$

So:

$$\begin{aligned}
L_{FP}(x, t) &= -\frac{\partial D^{(1)}(x, t)}{\partial x} + \frac{\partial^2 D^{(2)}(x, t)}{\partial x^2} \\
&\quad - \left[D^{(1)}(x, t) - 2 \frac{\partial D^{(2)}(x, t)}{\partial x} \right] \frac{\partial}{\partial x} + D^{(2)}(x, t) \frac{\partial^2}{\partial x^2}
\end{aligned}$$

Put it in 1 we can get:

$$\begin{aligned}
P(x, t + \tau | x', t) &= [1 + L_{KM}(x, t)\tau + \mathcal{O}(\tau^2)]\delta(x - x') \\
&= \left[1 - \tau \frac{\partial D^{(1)}(x, t)}{\partial x} + \tau \frac{\partial^2 D^{(2)}(x, t)}{\partial x^2} \right. \\
&\quad \left. - \tau \left(D^{(1)}(x, t) - 2 \frac{\partial D^{(2)}(x, t)}{\partial x} \right) \frac{\partial}{\partial x} + \tau D^{(2)}(x, t) \frac{\partial^2}{\partial x^2} + \mathcal{O}(\tau^2) \right] \delta(x - x') \\
&= \exp \left[-\tau \frac{\partial D^{(1)}(x, t)}{\partial x} + \tau \frac{\partial^2 D^{(2)}(x, t)}{\partial x^2} \right. \\
&\quad \left. - \tau \left(D^{(1)}(x, t) - 2 \frac{\partial D^{(2)}(x, t)}{\partial x} \right) \frac{\partial}{\partial x} + \tau D^{(2)}(x, t) \frac{\partial^2}{\partial x^2} + \mathcal{O}(\tau^2) \right] \delta(x - x') \\
&= \exp \left[-\tau \frac{\partial D^{(1)}(x, t)}{\partial x} + \tau \frac{\partial^2 D^{(2)}(x, t)}{\partial x^2} \right. \\
&\quad \left. - \tau \left(D^{(1)}(x, t) - 2 \frac{\partial D^{(2)}(x, t)}{\partial x} \right) \frac{\partial}{\partial x} + \tau D^{(2)}(x, t) \frac{\partial^2}{\partial x^2} + \mathcal{O}(\tau^2) \right] \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{iu(x-x')} du \\
&= \frac{1}{2\pi} \exp \left[-\tau \frac{\partial D^{(1)}(x, t)}{\partial x} + \tau \frac{\partial^2 D^{(2)}(x, t)}{\partial x^2} \right] \\
&\quad \times \int_{-\infty}^{\infty} \exp \left[iu \left(-\tau D^{(1)}(x, t) + 2\tau \frac{\partial D^{(2)}(x, t)}{\partial x} + (x - x') \right) - u^2 \tau D^{(2)}(x, t) \right] du
\end{aligned}$$

Final result is the answer of part b of Ex#3:

$$\begin{aligned}
P(x, t + \tau | x', t) &= \frac{1}{2} \sqrt{\frac{1}{\pi D^{(2)}(x, t) \tau}} \\
&\quad \times \exp \left(-\tau \frac{\partial D^{(1)}(x, t)}{\partial x} + \tau \frac{\partial^2 D^{(2)}(x, t)}{\partial x^2} - \frac{\left[(x - x') - \tau D^{(1)}(x, t) + 2\tau \frac{\partial D^{(2)}(x, t)}{\partial x} \right]^2}{4\tau D^{(2)}(x, t)} \right)
\end{aligned}$$

2. Equation of Ornstein-Uhlenbeck is as below:

$$\dot{\xi}_i + \gamma_{ij}\xi_j = \Gamma_i(t); \quad i = 1, \dots, N$$

We use Einstein sum rule on indices's and noise part have this properties $\langle \Gamma_i(t) \rangle = 0$ and $\langle \Gamma_i(t)\Gamma_j(t') \rangle = q_{ij}\delta(t-t')$. We have homogeneous and inhomogeneous solution with initial condition $\xi_i(0) = x_i$. For homogeneous part we have:

$$\dot{\xi}_i + \gamma_{ij}\xi_j = 0$$

Solution of above is $\xi_i^h(t) = G_{ij}(t)x_j$, with help of boundary condition we have:

$$\xi_i^h(0) = G_{ij}(0)x_j \Rightarrow G_{ij}(0) = \delta_{ij}$$

Homogeneous solution should satisfy on the equation so:

$$\begin{aligned} \frac{d}{dt}(G_{ij}x_j) + \gamma_{ik}G_{kj}x_j &= 0 \\ \dot{G}_{ij}x_j + G_{ij}\dot{x}_j + \gamma_{ik}G_{kj}x_j &= 0 \\ (\dot{G}_{ij} + \gamma_{ik}G_{kj})x_j + G_{ij}\dot{x}_j &= 0 \Rightarrow \text{We know that } \dot{x}_j = 0 \\ \dot{G}_{ij} + \gamma_{ik}G_{kj} &= 0 \quad \checkmark \end{aligned}$$

3. This problem is like path integral so we can write $p(x_0, t_0)$ with infinitesimal time difference $\tau = (t - t_0)/N$ when $N \rightarrow \infty$ so we have:

$$p(x, t) = \int dx_{N-1} \int dx_{N-1} \dots \int dx_0 p(x, t | x_{N-1}, t_{N-1}) p(x_{N-1}, t_{N-1} | x_{N-2}, t_{N-2}) \dots \\ \times p(x_1, t_1 | x_0, t_0) p(x_0, t_0)$$

By replacing 3 in above we have:

$$p(x, t) = \lim_{N \rightarrow \infty} \int dx_{N-1} \int dx_{N-2} \dots \int dx_0 \\ \left[4\pi D^{(2)}(x, t) \right]^{-1/2} \exp \left(- \frac{[x_1 - x_0 - D^{(1)}(x_0, t_0)\tau]^2}{4D^{(2)}(x_0, t_0)\tau} \right) \\ \times \left[4\pi D^{(2)}(x, t) \right]^{-1/2} \exp \left(- \frac{[x_2 - x_1 - D^{(1)}(x_1, t_1)\tau]^2}{4D^{(2)}(x_1, t_1)\tau} \right) \\ \times \dots \left[4\pi D^{(2)}(x, t) \right]^{-1/2} \exp \left(- \frac{[x_N - x_{N-1} - D^{(1)}(x_{N-1}, t_{N-1})\tau]^2}{4D^{(2)}(x_{N-1}, t_{N-1})\tau} \right) \\ = \lim_{N \rightarrow \infty} \int dx_{N-1} \int dx_{N-2} \dots \int dx_0 \prod_{i=0}^{N-1} \left[4\pi D^{(2)}(x_i, t_i) \right]^{-1/2} \\ \times \exp \left(- \sum_{i=0}^{N-1} \frac{[x_{i+1} - x_i - D^{(1)}(x_i, t_i)\tau]^2}{4D^{(2)}(x_i, t_i)\tau} \right) p(x_0, t_0)$$

If evolution equation be like $x_{i+1} - x_i = \dot{x}(t_i)\tau$ we can write:

$$\sum_{i=0}^{N-1} \frac{[\dot{x}(t_i) - D^{(1)}(x_i, t_i)]^2}{4D^{(2)}(x_i, t_i)} \tau = \int_{t_0}^t \frac{[\dot{x}(t') - D^{(1)}(x(t'), t')]^2}{4D^{(2)}(x(t'), t')} dt'$$

This called generalized Onsager-Machlup equation.